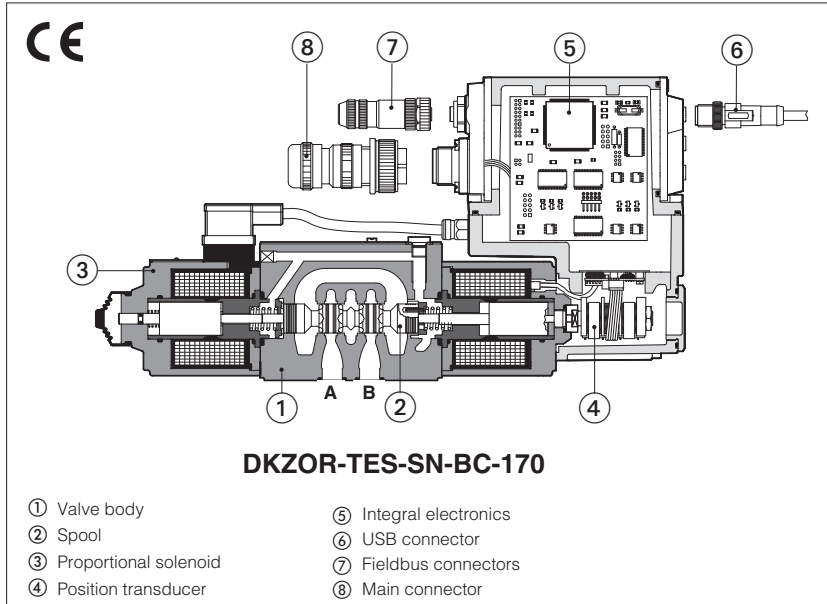


# Servoproportional directional valves

**digital**, direct operated, with position transducer and **zero spool overlap**, rugged design



**DHZO-TEB, DHZO-TES  
DKZOR-TEB, DKZOR-TES**

Servoproportional direct operated digital proportional valves with LVDT position transducer and zero spool overlap for position closed loop controls. The double solenoid construction involves larger flows and central safety rest position.

The integral digital electronic driver performs the valve's hydraulic regulation according to the reference signal and assures valve-to-valve interchangeability thanks to the factory presetting.

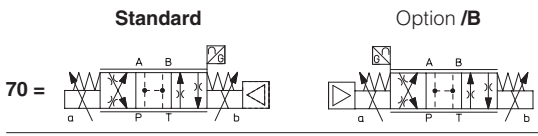
Servoproportional valves are available in TEB basic execution with analog reference signals and USB port for software functional parameters setting or in TES full execution which includes also optional alternated P/Q controls and fieldbus interfaces for functional parameters setting, reference signals and real-time diagnostics.

Size: **06** and **10**  
Max flow: up to **75** and **170 l/min**  
Max pressure: **350 bar** (DHZO)  
**315 bar** (DKZOR)

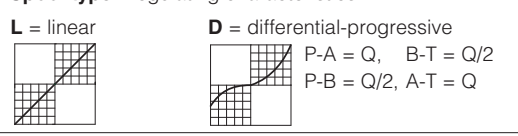
**1 MODEL CODE**

<b>DHZO</b>	-	<b>T</b>	-	<b>ES</b>	-	<b>SN</b>	-	<b>NP</b>	-	<b>0</b>	<b>70</b>	-	<b>L</b>	<b>5</b>	/	<b>*</b>	/	<b>*</b>								
<p><b>DHZO</b> = size 06 <b>DKZOR</b> = size 10</p>		<p><b>T</b> = closed-loop one LVDT transducer</p>		<p><b>Integral digital drivers:</b> <b>EB</b> = basic (1) <b>ES</b> = full</p>		<p><b>Alternated P/Q controls</b>, see section 4: <b>SN</b> = none (1) <b>SP</b> = pressure control (1 pressure transducer) <b>SF</b> = force control (2 pressure transducers) <b>SL</b> = force control (1 load cell)</p>		<p><b>Fieldbus interfaces</b>, USB port always present: <b>NP</b> = Not present (1) <b>BC</b> = CANopen      <b>EH</b> = EtherCAT <b>BP</b> = PROFIBUS DP    <b>EI</b> = EtherNet/IP <b>EW</b> = POWERLINK    <b>EP</b> = PROFINET IRT</p>		<p><b>Valve size</b> ISO 4401: <b>0</b> = 06    <b>1</b> = 10</p>		<p><b>Seals material</b>, see sections 6, 7: - = NBR <b>PE</b> = FKM <b>BT</b> = HNBR</p> <p>Series number</p>		<p><b>Hydraulic options</b>, see section 11: <b>B</b> = solenoid with integral electronics and position transducer at side of port A (2) <b>Y</b> = external drain</p> <p><b>Electronic options</b>, see section 12: Note: <b>F, Q, Z</b> options are standard for <b>SP, SF, SL</b> <b>C</b> = current feedback for pressure transducer 4÷20mA (omit for std voltage ±10Vdc) only <b>TES-SP, SF, SL</b> <b>F</b> = fault signal - only <b>TEB</b> and <b>TES-SN</b> <b>I</b> = current reference input and monitor 4÷20mA (omit for standard ±10Vdc) <b>Q</b> = enable signal - only <b>TEB</b> and <b>TES-SN</b> <b>Z</b> = double power supply, enable, fault and monitor signals - 12 pin connector (3)</p> <p><b>Safety option</b> TUV certified - only <b>TES</b>: <b>U</b> = safe double power supply See technical table <b>FY100</b></p>		<p><b>Spool size:</b></p> <table border="0"> <tr> <td></td> <td style="text-align: center;"><b>3 (L)</b></td> <td style="text-align: center;"><b>5 (L,D)</b></td> </tr> <tr> <td>DHZO</td> <td style="text-align: center;">= 17</td> <td style="text-align: center;">28</td> </tr> <tr> <td>DKZOR</td> <td style="text-align: center;">= 45</td> <td style="text-align: center;">75</td> </tr> </table> <p>Nominal flow (l/min) at Δp 10bar P-T</p>			<b>3 (L)</b>	<b>5 (L,D)</b>	DHZO	= 17	28	DKZOR	= 45	75
	<b>3 (L)</b>	<b>5 (L,D)</b>																								
DHZO	= 17	28																								
DKZOR	= 45	75																								

**Configuration:**



**Spool type - regulating characteristics:**



(1) TEB is available only in version SN-NP  
(2) In standard configuration the solenoid with integral electronics and position transducer are at side of port B

(3) double power supply only for TES



## 2 GENERAL NOTES

DHZO-TEs, TEB and DKZOR-TEs are CE marked according to the applicable Directives (e.g. Immunity/Emission EMC Directive and Low Voltage Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in table F003 and in the installation notes supplied with relevant components. The electrical signals of the valve (e.g. monitor signals) must not be directly used to activate safety functions or components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

## 3 AXIS CONTROLLER

Digital servoproportional with integral electronics **TEZ** include valve's driver plus axis controller, performing position closed loop of any hydraulic actuator equipped with analog, encoder or SSI position transducer. S\* option add alternated P/Q control to the basic position ones.

For detailed information about integral axis controller see tech table **FS230**.

Atos also supply complete servoactuators integrating servocylinder, digital servoproportional valve and axis controller, fully assembled and tested. For more information consult Atos Technical Office.

## 4 ALTERNATED P/Q CONTROLS - only for TES

**S\*** options add the closed loop control of pressure (**SP**) or force (**SF** and **SL**) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions.

An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers for SF or 1 load cell for SL). Main 12 pin connector is the same as /Z option plus two analog signals specific for the pressure (force) control.

For detailed information and connector wiring of options SP, SF, SL see tech table **GS212**.

**Note:** for proportional valve with zero overlapped spool the alternated pressure control (SP) is possible only for specific installation conditions, see tech. table GS212

## 5 FIELDBUS - only for TES

Fieldbus allows the direct communication of the proportional valve with machine control unit for digital reference signal, diagnostics and settings of functional parameters. Analog reference signal remain available on the main connector for quick commissioning and maintenance.

For detailed information about fieldbus features and specification see tech table **GS510**.

## 6 MAIN CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Assembly position	Any position			
Subplate surface finishing	Roughness index, Ra 0,4 flatness ratio 0,01/100 (ISO 1101)			
MTTFd values according to EN ISO 13849	150 years, see technical table P007			
Ambient temperature range	<b>standard</b> = -20°C ÷ +60°C		<b>/BT</b> option = -40°C ÷ +60°C	
Storage temperature range	<b>standard</b> = -20°C ÷ +70°C		<b>/BT</b> option = -40°C ÷ +70°C	
Coil resistance R at 20°C	<b>DHZO</b> = 3 ÷ 3,3 Ω		<b>DKZOR</b> = 3,8 ÷ 4,1 Ω	
Max. solenoid current	<b>DHZO</b> = 2,6 A		<b>DKZOR</b> = 3 A	
Max. power	50 Watt			
Insulation class	H (180°) Due to the occurring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN 982 must be taken into account			
Protection degree to DIN EN60529	IP66/67 with mating connector			
Tropicalization	Tropical coating on electronics PCB			
Duty factor	Continuous rating (ED=100%)			
EMC, climate and mechanical load	See technical table G004			
Communication interface	USB	CANopen	PROFIBUS DP	EtherCAT, POWERLINK
	Atos ASCII coding	EN50325-4 + DS408	EN50170-2/IEC61158	EtherNet/IP, PROFINET IO RT/ IRT IEC 61158
Communication physical layer	not insulated	optical insulated	optical insulated	Fast Ethernet, insulated
	USB 2.0 + USB OTG	CAN ISO11898	RS485	100 Base TX

Valve model	DHZO			DKZOR		
Pressure limits [bar]	ports <b>P, A, B</b> = 350; <b>T</b> = 210 (250 with external drain /Y); <b>Y</b> = 10			ports <b>P, A, B</b> = 315; <b>T</b> = 210 (250 with external drain /Y); <b>Y</b> = 10		
Spool type	<b>L3</b>	<b>L5</b>	<b>D5</b>	<b>L3</b>	<b>L5</b>	<b>D5</b>
Nominal flow [l/min]						
(1) $\Delta p = 10$ bar	18	28	28	45	75	75
$\Delta p$ P-T $\Delta p = 30$ bar	30	50	50	80	130	130
max $\Delta p = 70$ bar	45	75	75	120	170	170
permissible flow (2)	50	80	80	130	180	180
Response time [ms] (0-100% step signal) (3)	< 15			< 20		
Leakage [cm <sup>3</sup> ]	<500 (at p = 100 bar); <1500 (at p = 350 bar)			<800 (at p = 100 bar); <2500 (at p = 315 bar)		
Hysteresis	≤ 0,2 [% of max regulation]					
Repeatability	± 0,1 [% of max regulation]					
Thermal drift	zero point displacement < 1% at $\Delta T = 40^\circ C$					

### Notes:

above performance data refer to valves coupled with Atos electronic drivers, see section 8.

(1) for different  $\Delta p$ , the max flow is in accordance to the diagrams in section 9.2 (2) see detailed diagrams in section 9.3

(3) see detailed diagrams in section 9.4

**7 SEALS AND HYDRAULIC FLUID** - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature	NBR seals (standard) = -20°C ÷ +60°C, with HFC hydraulic fluids = -20°C ÷ +50°C FKM seals (/PE option) = -20°C ÷ +80°C HNBR seals (/BT option) = -40°C ÷ +60°C, with HFC hydraulic fluids = -40°C ÷ +50°C		
Recommended viscosity	20 ÷ 100 mm <sup>2</sup> /s - max allowed range 15 ÷ 380 mm <sup>2</sup> /s		
Fluid contamination class	ISO 4406 class 20/18/15 NAS 1638 class 9, in line filters of 10 µm (β10 ≥75 recommended)		
<b>Hydraulic fluid</b>	<b>Suitable seals type</b>	<b>Classification</b>	<b>Ref. Standard</b>
Mineral oils	NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524
Flame resistant without water	FKM	HFDU, HFDR	ISO 12922
Flame resistant with water	NBR, HNBR	HFC	

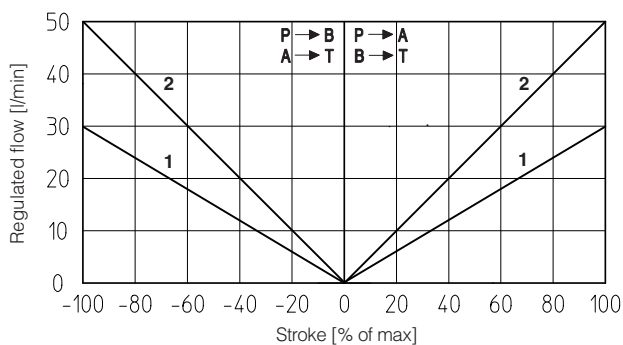
**8 ELECTRONIC DRIVERS**

Valve model	<b>TEB</b>	<b>TES</b>	<b>TES-SP, SF, SL</b>	<b>TEZ</b>
Drivers model	E-RI-TEB-N	E-RI-TES-N	E-RI-TES-S	E-RI-TEZ
Type	Digital			
Format	Integral to valve			
Data sheet	GS208	GS210	GS212	FS230

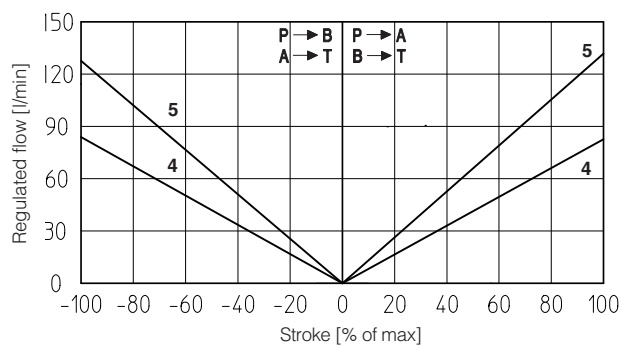
**Note:** for main and communication connectors see sections [12](#), [13](#)

**9 DIAGRAMS** - based on mineral oil ISO VG 46 at 50 °C

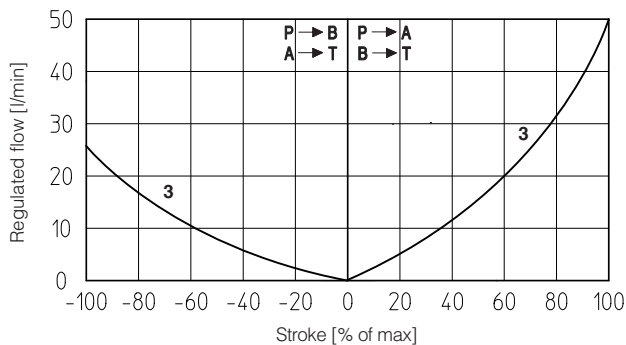
**9.1 Regulation diagrams** (values measure at Δp 30 bar P-T)



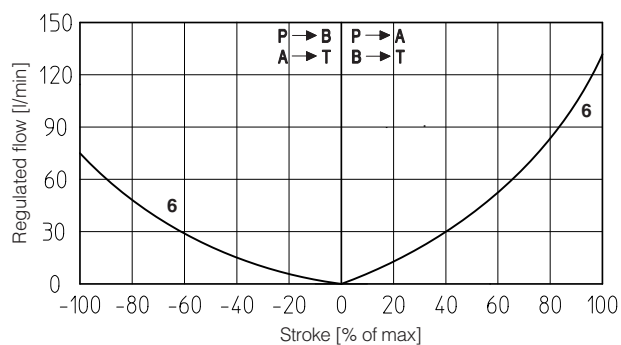
**DHZO**  
1 = L3 2 = L5



**DKZOR**  
4 = L3 5 = L5



**DHZO**  
3 = D5



**DKZOR**  
6 = D5

**Note:**

Hydraulic configuration vs. reference signal for configurations 70 (standard and option /B)

Reference signal  $\left. \begin{matrix} 0 \div +10 \text{ V} \\ 12 \div 20 \text{ mA} \end{matrix} \right\} P \rightarrow A / B \rightarrow T$       Reference signal  $\left. \begin{matrix} 0 \div -10 \text{ V} \\ 12 \div 4 \text{ mA} \end{matrix} \right\} P \rightarrow B / A \rightarrow T$

### 9.2 Flow /Dp diagrams

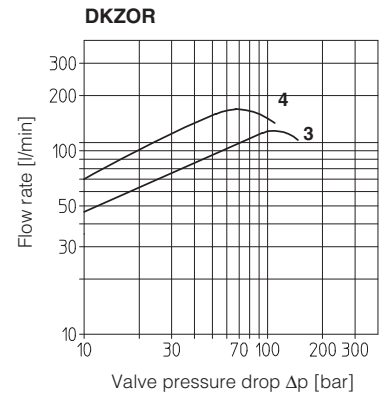
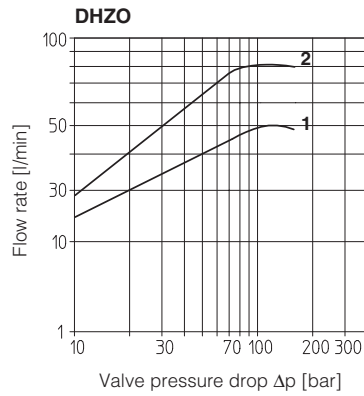
stated at 100% of valve stroke

#### DHZO

- 1 = spool L3,
- 2 = spool L5, D5

#### DKZOR

- 3 = spool L3
- 4 = spool L5, D5



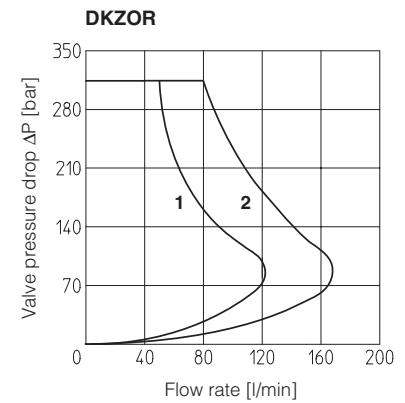
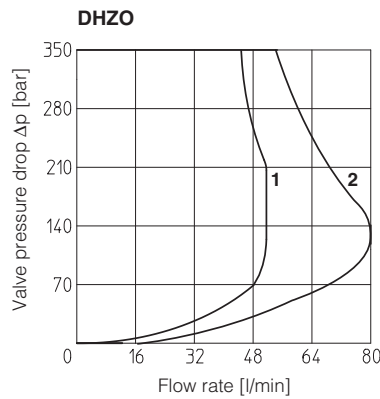
### 9.3 Operating limits

#### DHZO

- 1 = spool L3
- 2 = spool L5, D5

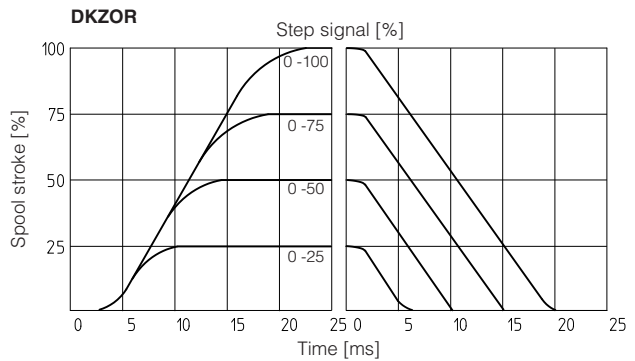
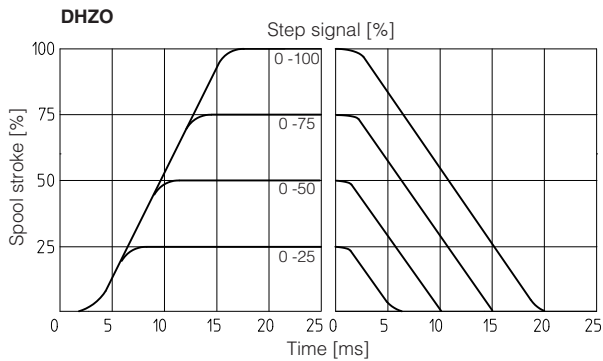
#### DKZOR

- 3 = spool L3
- 4 = spool L5, D5



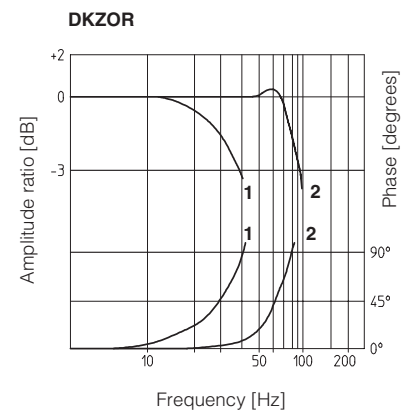
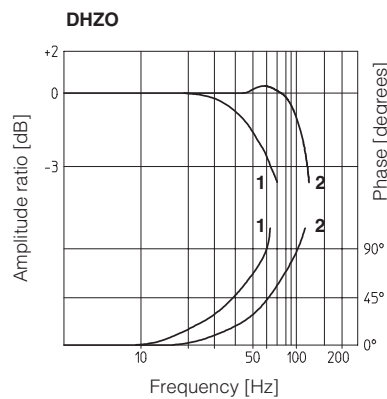
### 9.4 Response time

The response times in below diagrams are measured at different steps of the reference input signal. They have to be considered as average values. For the valves with digital electronics the dynamics performances can be optimized by setting the internal software parameters.



### 9.5 Bode diagrams

- 1 = 10% ↔ 90% nominal stroke
- 2 = 50% ± 5% nominal stroke



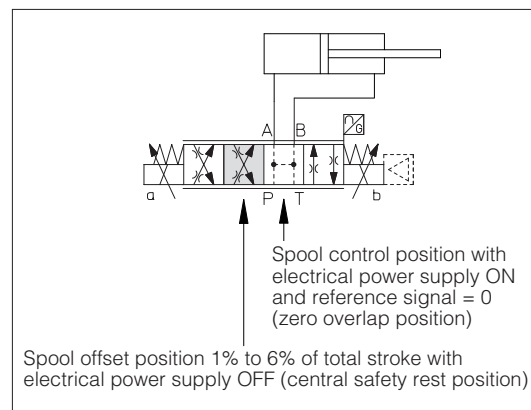
## 10 CENTRAL SAFETY REST POSITION OF ZERO SPOOL OVERLAP - configuration 70

In absence of electric power supply (+24 VDC), the valve spool is moved by the springs force to the **central safety rest position** characterized by a small offset of about 1% to 6% of the total stroke in P-B / A-T configuration.

This is specifically designed to avoid that in case of accidental interruption of the electrical power supply to the valve, the actuator moves towards an undefined direction (due to the tolerances of the zero overlap spool), with potential risk of damages or personnel injury.

Thanks to the **central safety rest position** the actuator movement is suddenly stopped and it is recovered at very low speed towards the direction corresponding to the P-B/ A-T connection.

The spool moves to the closed loop control position (zero overlap) when the valve is fed with power supply +24 VDC and reference input = 0V (or 12 mA for option /I) is applied to the driver.



## 11 HYDRAULIC OPTIONS

### 11.1 Option /B

Solenoid, integral electronics and position transducer at side of port A of the main stage.  
For hydraulic configuration vs reference signal, see section 9.1

### 11.2 Option /Y

Option /Y is mandatory if the pressure in port T exceeds 210 bar.

## 12 ELECTRONIC OPTIONS

Standard driver execution provides on the 7 pin main connector:

**Power supply** - 24 VDC must be appropriately stabilized or rectified and filtered; 2,5 A fuse time lag is required in series to each driver power supply. Apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers

**Reference input signal** - analog differential input with  $\pm 10$  VDC nominal range (pin D, E), proportional to desired valve spool position

**Monitor output signal** - analog output signal proportional to the actual valve's spool position with  $\pm 10$ VDC nominal range

**Note:** a minimum booting time between 400 and 800 ms has to be considered from the driver energizing with the 24 Vdc power supply before the valve has been ready to operate. During this time the current to the valve coils is switched to zero.

### 12.1 Option /F

It provides a Fault output signal in place of the Monitor output signal, to indicate fault conditions of the driver (cable interruption of spool transducers or reference signal - for /I option): Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC

### 12.2 Option /I

It provides 4  $\div$  20 mA current reference and monitor signals, instead of the standard  $\pm 10$  V.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  V or  $\pm 20$  mA.

It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

### 12.3 Option /Q

To enable the driver, supply 24 VDC on pin C referred to pin B: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to maintain active the communication and the other driver functions when the valve has to be disabled. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

### 12.4 Option /Z

It provides, on the 12 pin main connector, the following additional features:

#### Enable Input Signal

To enable the driver, supply 24 VDC on pin 3 referred to pin 2: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to maintain active the communication and the other driver functions when the valve has to be disabled. This condition does not comply with European Norms EN13849-1 (ex EN954-1).

#### Fault Output Signal

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 $\div$ 20mA input, etc.). Fault presence corresponds to 0 Vdc, normal working corresponds to 24 VDC (pin 11 referred to pin 2): Fault status is not affected by the Enable input signal

#### Power supply for driver's logics and communication - only for TES

Separate power supply (pin 9,10) allow to cut solenoid power supply (pin 1,2) while maintaining active diagnostics, USB and fieldbus communication. A safety fuse is required in series to each driver power supply: 500 mA fast fuse.

### 12.5 Options /C - only for SP, SF, SL

Option /C is available to connect pressure (force) transducers with 4  $\div$  20 mA current output signal, instead of the standard  $\pm 10$  V.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  V or  $\pm 20$  mA.

### 12.6 Possible combined options

For SN: /FI, /IQ and /IZ

For SP, SF, SL: /CI

### 13 ELECTRONIC CONNECTIONS AND LEDS

#### 13.1 Main connector signal - 7 pin - standard, /F and /Q options (A1)

PIN	Standard	/Q	/F	TECHNICAL SPECIFICATIONS	NOTES
A	V+			Power supply 24 Vdc Rectified and filtered: $V_{RMS} = 20 \div 32 V_{MAX}$ (ripple max 10 % VPP)	Input - power supply
B	V0			Power supply 0 Vdc	Gnd - power supply
C	AGND		AGND	Analog ground	Gnd - analog signal
		ENABLE		Enable (24 Vdc) or disable (0 Vdc) the valve, referred to V0	Input - on/off signal
D	Q_INPUT+			Flow reference input signal: $\pm 10 Vdc / \pm 20 mA$ maximum range Defaults are $\pm 10 Vdc$ for standard and $4 \div 20 mA$ for /I option	Input - analog signal <b>Software selectable</b>
E	INPUT-			Negative reference input signal for Q_INPUT+	Input - analog signal
F	Q_MONITOR referred to: AGND V0			Flow monitor output signal: $\pm 10 Vdc / \pm 20 mA$ maximum range Defaults are $\pm 10 Vdc$ for standard and $4 \div 20 mA$ for /I option	Output - analog signal <b>Software selectable</b>
			FAULT	Fault (0 Vdc) or normal working (24 Vdc)	Output - on/off signal
G	EARTH			Internally connected to the driver housing	

#### 13.2 Main connector signal - 12 pin - /Z option and SP, SF, SL (A2)

PIN	TEB-SN /Z	TES-SN /Z	TES-SP, SF, SL Fieldbus NP		TECHNICAL SPECIFICATIONS	NOTES
1	V+				Power supply 24 Vdc Rectified and filtered: $V_{RMS} = 20 \div 32 V_{MAX}$ (ripple max 10 % VPP)	Input - power supply
2	V0				Power supply 0 Vdc	Gnd - power supply
3	ENABLE referred to: V0 VL0 VL0 V0				Enable (24 Vdc) or disable (0 Vdc) the valve	Input - on/off signal
4	Q_INPUT+				Flow reference input signal: $\pm 10 Vdc / \pm 20 mA$ maximum range Defaults are $\pm 10 Vdc$ for standard and $4 \div 20 mA$ for /I option	Input - analog signal <b>Software selectable</b>
5	INPUT-				Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
6	Q_MONITOR referred to: AGND VL0 VL0 V0				Flow monitor output signal: $\pm 10 Vdc / \pm 20 mA$ maximum range Defaults are $\pm 10 Vdc$ for standard and $4 \div 20 mA$ for /I option	Output - analog signal <b>Software selectable</b>
	AGND	NC			Analog ground Do not connect	Gnd - analog signal
7			F_INPUT+		Pressure/Force reference input signal: $\pm 10 Vdc / \pm 20 mA$ maximum range Defaults are $\pm 10 Vdc$ for standard and $4 \div 20 mA$ for /I option	Input - analog signal <b>Software selectable</b>
	8	R_ENABLE	NC		Repeat enable, output repeter signal of enable input, referred to V0 Do not connect	Output - on/off signal
9			F_MONITOR referred to: VL0 V0		Pressure/Force monitor output signal: $\pm 10 Vdc / \pm 20 mA$ maximum range Defaults are $\pm 10 Vdc$ for standard and $4 \div 20 mA$ for /I option	Output - analog signal <b>Software selectable</b>
	9	NC	VL+		Do not connect Power supply 24 Vdc for driver's logic and communication	Input - power supply
10			D_IN0		Multiple pressure/force PID selection, referred to V0	Input - analog signal
	10	NC	VL0		Do not connect Power supply 0 Vdc for driver's logic and communication	Gnd - power supply
11			D_IN1		Multiple pressure/force PID selection (not available for SF), referred to V0	Input - on/off signal
	11	FAULT referred to: V0 VL0 VL0 VL0				Fault (0 Vdc) or normal working (24 Vdc)
PE	EARTH				Internally connected to the driver housing	

**Note:** do not disconnect VL0 before VL+ when the driver is connected to PC USB port

#### 13.4 Communications connectors (B) - (C)

(B) USB connector - M12 - 5 pin always present		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	+5V_USB	Supply for external USB Flash Drive
2	ID	USB Flash Drive identification
3	GND_USB	Signal zero data line
4	D-	Data line -
5	D+	Data line +

(C1) (C2) BP fieldbus execution, connector - M12 - 5 pin		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	+5V	Termination supply signal
2	LINE-A	Bus line (high)
3	DGND	Data line and termination signal zero
4	LINE-B	Bus line (low)
5	SHIELD	

(C1) (C2) BC fieldbus execution, connector - M12 - 5 pin		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	CAN_SHLD	Shield
2	not used	(C1) - (C2) pass-through connection (2)
3	CAN_GND	Signal zero data line
4	CAN_H	Bus line (high)
5	CAN_L	Bus line (low)

(C1) (C2) EH, EW, EI, EP fieldbus execution, connector - M12 - 4 pin		
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)
1	TX+	Transmitter
2	RX+	Receiver
3	TX-	Transmitter
4	RX-	Receiver
Housing	SHIELD	

**Notes:** (1) shield connection on connector's housing is recommended

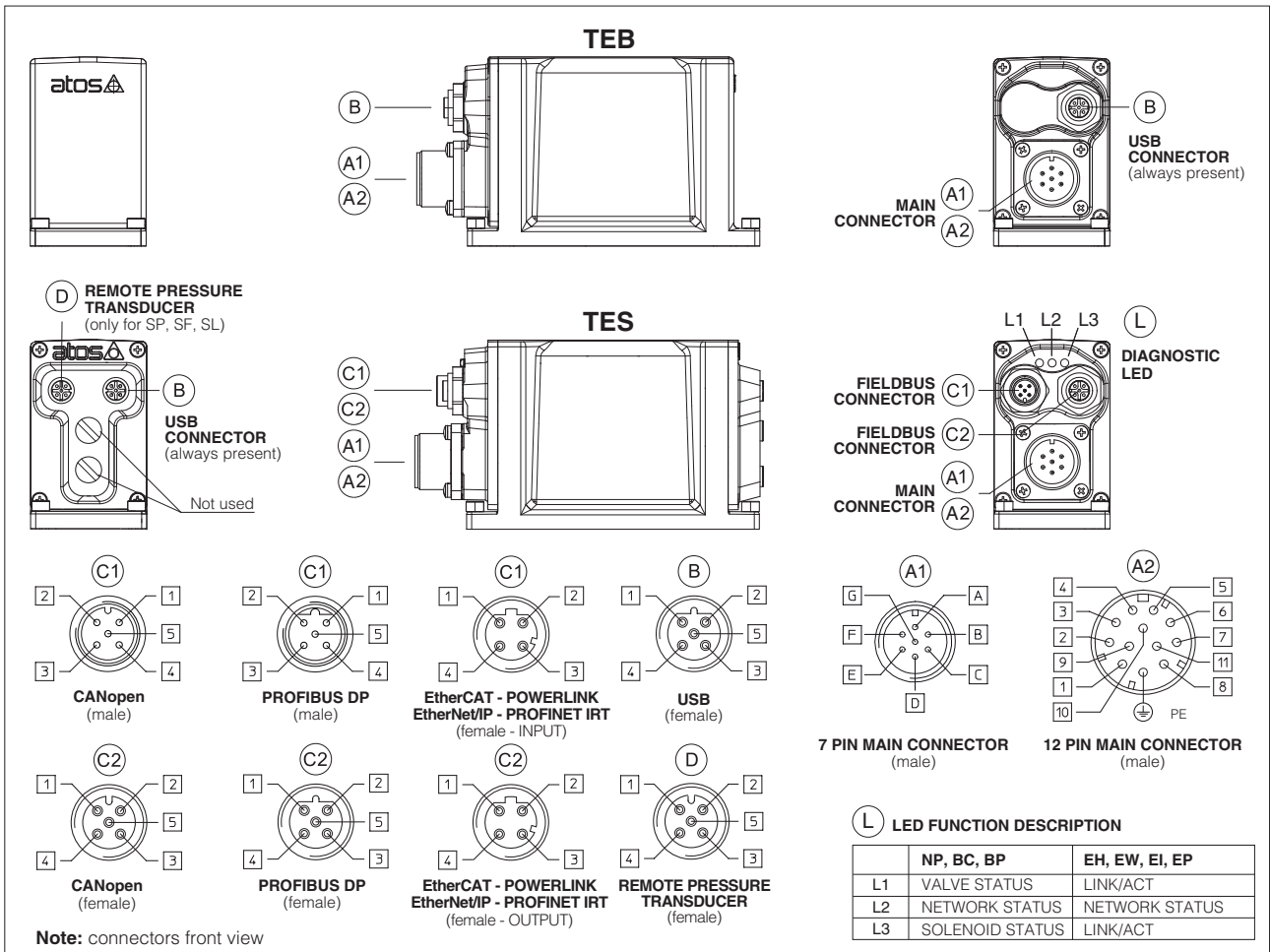
(2): pin 2 can be fed with external +5V supply of CAN interface

#### 13.5 Remote pressure/force transducer connector - M12 - 5 pin - only for SP, SF, SL (D)

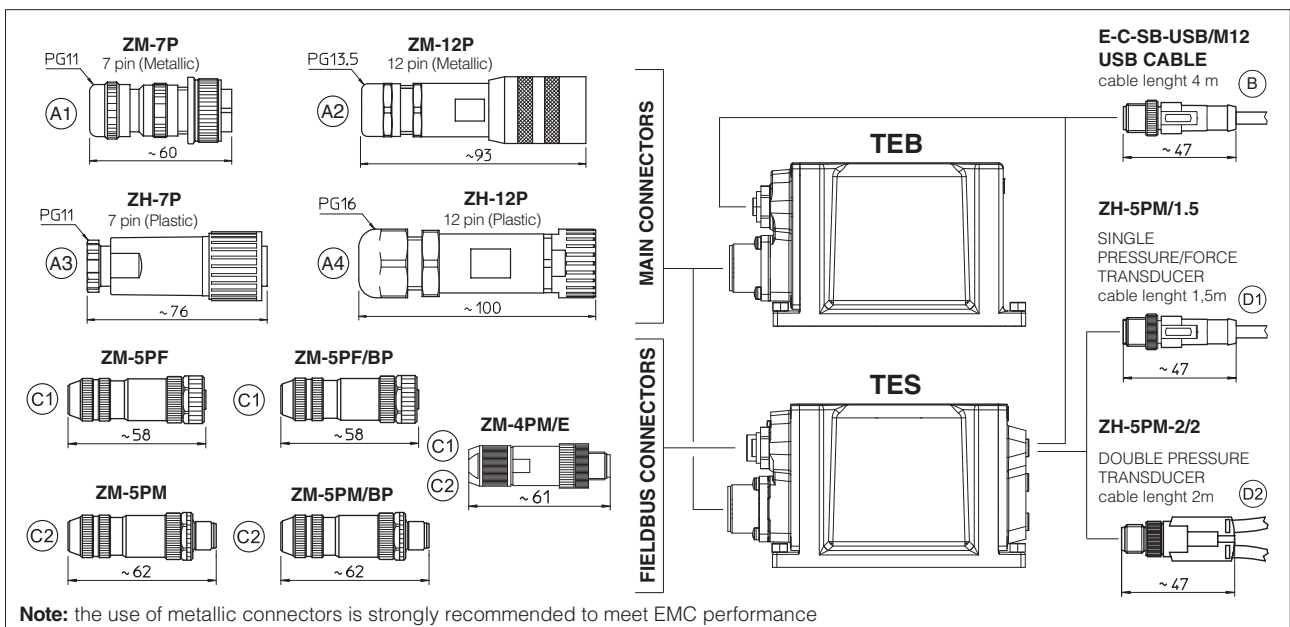
PIN	SIGNAL	TECHNICAL SPECIFICATION	Single transducer (1)		Double transducers (1)	
			Voltage	Current	Voltage	Current
1	VF +24V	Power supply +24Vdc	Connect	Connect	Connect	Connect
2	TR1	1st signal transducer: $\pm 10 Vdc / \pm 20 mA$ maximum range, software selectable Defaults are $\pm 10 Vdc$ for standard and $4 \div 20 mA$ for /C option	Connect	Connect	Connect	Connect
3	AGND	Common GND for transducer power and signals	Connect	/	Connect	/
4	TR2	2nd signal transducer: $\pm 10 Vdc / \pm 20 mA$ maximum range, software selectable Defaults are $\pm 10 Vdc$ for standard and $4 \div 20 mA$ for /C option	/	/	Connect	Connect
5	NC	Not connect	/	/	/	/

**Note (1)** single/double transducer configuration is software selectable

### 13.5 Connections layout



### 14 CONNECTORS



### 15 MODEL CODES OF MAIN CONNECTORS AND COMMUNICATION CONNECTORS - to be ordered separately

VALVE VERSION	TEB TES	TEB /Z TES /Z	BC	BP	EH, EW, EI, EP	P/Q controls SP, SL, SF
CONNECTOR CODE	ZM-7P (A1)	ZM-12P (A2)	ZM-5PF (C1)	ZM-5PF/BP (C1)	ZM-4PM/E (C1)	ZH-5PM/1.5 (1) (D1)
	ZH-7P (A3)	ZH-12P (A4)	ZM-5PM (C2)	ZM-5PM/BP (C2)	ZM-4PME (C2)	ZH-5PM-2/2 (2) (D2)
PROTECTION DEGREE	IP67					
DATA SHEET	GS208, GS210, GS212, K500					

only for TES

(1) only for SP or SL

(2) only for SF

**15 PROGRAMMING TOOLS** - see table **GS500**

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver. For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

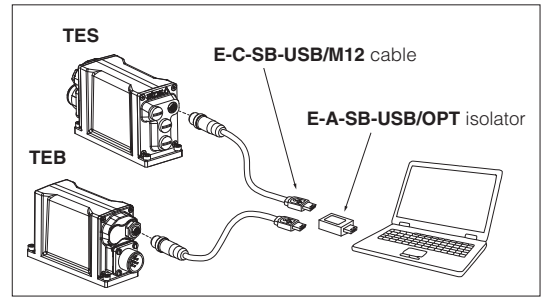
The software is available in different versions according to the driver's options:

**E-SW-BASIC** support: NP (USB) PS (Serial) IR (Infrared)  
**E-SW-FIELDBUS** support: BC (CANopen) BP (PROFIBUS DP) EH (EtherCAT)  
 EW (POWERLINK) EI (EtherNet/IP) EP (PROFINET IRT)  
**E-SW-\*/PQ** support: valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

**WARNING: drivers USB port is not isolated!**

The use of isolator adapter is highly recommended for PC protection (see table **GS500**)

**USB connection**



**17 INSTALLATION DIMENSIONS [mm]**

**DHZO-TEB, DHZO-TES**

ISO 4401: 2000

Mounting surface: 4401-03-02-0-05 (see table P005)

(for /Y surface 4401-03-03-0-05 without X port)

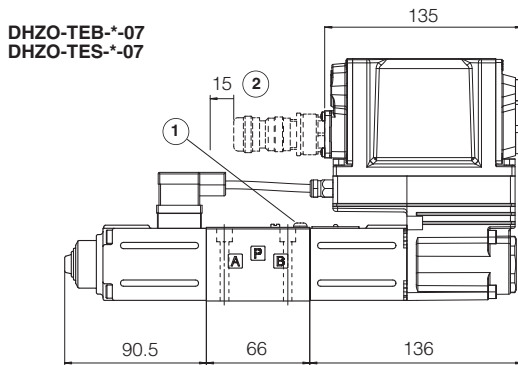
Fastening bolts: 4 socket head screws M5x50 class 12.9

Tightening torque = 8 Nm

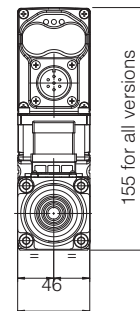
Seals: 4 OR 108; 1 OR 2025

Diameter of ports A, B, P, T: Ø 7,5 mm (max)

Diameter of port Y: Ø = 3,2 mm (only for /Y option)



Mass: 3,1 kg



**DKZOR-TEB, DKZOR-TES**

ISO 4401: 2000

Mounting surface: 4401-05-04-0-05 (see table P005)

(for /Y surface 4401-05-05-0-05 without X port)

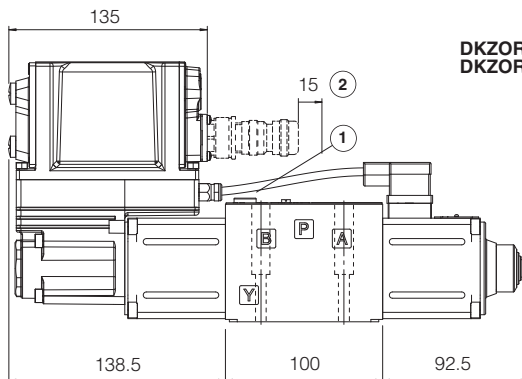
Fastening bolts: 4 socket head screws M6x40 class 12.9

Tightening torque = 15 Nm

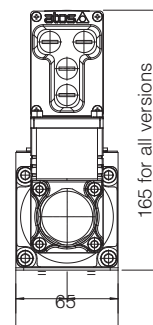
Seals: 5 OR 2050; 1 OR 108

Diameter of ports A, B, P, T: Ø 11,2 mm (max)

Diameter of port Y: Ø = 5 mm (only for /Y option)



Mass: 5,0 kg



① = Air bleed off

② = Space to remove 7 or 12 pin the main connector - for main and communication connectors see section 14, 15