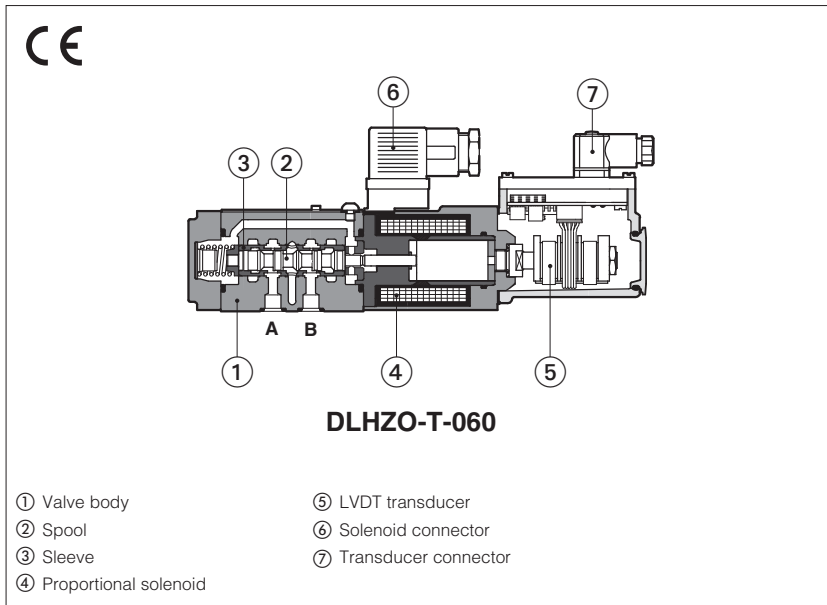


Servoproportional directional valves sleeve execution

direct, with LVDT transducer and zero spool overlap with fail safe



DLHZO-T, DLKZOR-T

Servoproportional directional valves, direct, with LVDT position transducer and zero spool overlap for best performances in any position closed loop.

The valves operate in association with digital off-board divers or axis card, see section 2.

The LVDT transducer and the sleeve execution grant very high regulation accuracy and response sensitivity.

The fail safe position permits to intercept the actuator movement in case of power supply interruption.

Spools regulation characteristics:

L = linear

V = progressive

T = non linear for fine low flow control

D and DT = differential, for control of actuators with area ratio 1:2

DLHZO:

Size: **06** - ISO 4401

Max flow: **70 l/min**

Max pressure: **350 bar**

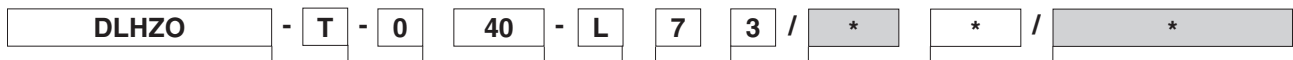
DLKZOR:

Size: **10** - ISO 4401

Max flow: **130 l/min**

Max pressure: **315 bar**

1 MODEL CODE



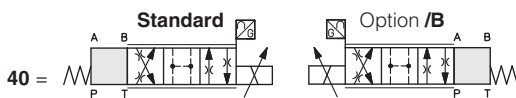
DLHZO = size 06
DLKZOR = size 10

T = with LVDT transducer

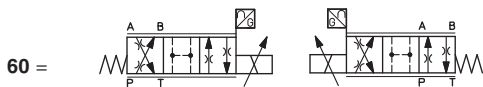
Valve size ISO 4401:

0 = 06 **1** = 10

Configuration:



with fail safe configuration 1 or 3



without fail safe

Spool type, regulating characteristics:

L = linear

V = progressive

T = not linear (1)



D = differential-linear (1)

DT = differential-not linear (1)



P-A = Q, B-T = Q/2
P-B = Q/2, A-T = Q



P-A = Q, B-T = Q/2
P-B = Q/2, A-T = Q

Seals material, see section 6:

- = NBR

PE = FKM

BT = HNBR

Series number

Hydraulic options (2):

B = solenoid and LVDT transducer at side of port A

Y = external drain

Fail safe configuration, see section 8:



Note: select **1** for configuration **60** even without fail safe

Spool size: **0(L)** **1(L)** **1(V)** **3(L)** **3(T)** **3(V)** **5(L,T)** **7(L,T,V,D,DT)**

DLHZO = 4 7 12 14 - 20 28 40

DLKZOR = - - - 60 60 - - 100

Nominal flow (l/min) at Δp 70bar P-T

(1) Not available for configuration **60**

(2) Possible combined options: /BY

2 OFF-BOARD ELECTRONIC DRIVERS

Please include in the driver order also the complete code of the connected proportional valve.

Drivers model	E-BM-TEB	E-BM-TES	Z-BM-TEZ
Type	Digital	Digital	Digital
Format	DIN-rail panel	DIN-rail panel	DIN-rail panel
Tech table	GS230	GS240	GS330

3 GENERAL CHARACTERISTICS

Assembly position	Any position
Subplate surface finishing to ISO 4401	Acceptable roughness index: Ra ≤ 0,8, recommended Ra 0,4 – Flatness ratio 0,01/100
MTTFd valves according to EN ISO 13849	150 years, see technical table P007
Ambient temperature range	Standard = -20°C ÷ +60°C /PE option = -20°C ÷ +60°C /BT option = -40°C ÷ +60°C
Storage temperature range	Standard = -20°C ÷ +70°C /PE option = -20°C ÷ +70°C /BT option = -40°C ÷ +70°C
Surface protection	Zinc coating with black passivation
Corrosion resistance	Salt spray test (EN ISO 9227) > 200 h
Compliance	CE according to EMC directive 2014/30/EU (Immunity: EN 61000-6-2; Emission: EN 61000-6-3) RoHS Directive 2011/65/EU as last update by 2015/863/EU REACH Regulation (EC) n°1907/2006

4 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model	DLHZO											DLKZOR							
	ports P, A, B = 350; T = 210 (250 with external drain /Y) Y = 10											ports P, A, B = 315; T = 210 (250 with external drain /Y) Y = 10							
Pressure limits [bar]	L0	L1	V1	L3	V3	L5	T5	L7	T7	V7	D7	DT7	L3	T3	L7	T7	V7	D7	DT7
Spool type																			
Nominal flow Δp P-T [l/min] (1)																			
Δp = 30 bar	2,5	4,5	8	9	13	18		26			26÷13 (4)		40		60			60÷33 (4)	
Δp = 70 bar	4	7	12	14	20	28		40			40÷20 (4)		60		100			100÷50 (4)	
Max permissible flow	8	14	16	30	40	50		70			70÷40 (4)		110		130			130÷65 (4)	
Leakage (2) [cm ³ /min]	<100	<200	<100	<300	<150	<500	<200	<900	<200	<200	<700	<200	<1000	<400	<1500	<400	<400	<1200	<400
Response time (3) [ms]	≤ 10											≤ 15							
Hysteresis	≤ 0,1 [% of max regulation]																		
Repeatability	± 0,1 [% of max regulation]																		
Thermal drift	zero point displacement < 1% at ΔT = 40°C																		

(1) For different Δp , the max flow is in accordance to the diagrams in section 7.2

(2) Referred to spool in neutral position and 50°C oil temperature

(3) 0-100% step signal

(4) For spool type D7 and DT7 the flow value is referred to single path P-A (A-T) ÷ P-B (B-T) at $\Delta p/2$ per control edge

5 ELECTRICAL CHARACTERISTICS

Max power consumption	30 W
Max. solenoid current	DLHZO = 2,6 A DLKZOR = 3 A
Coil resistance R at 20°C	DLHZO = 3 ÷ 3,3 Ω DLKZOR = 2,2 ÷ 2,4 Ω
Insulation class	H (180°) Due to the occurring surface temperatures of the solenoid coils, the European standards ISO 13732-1 and EN982 must be taken into account
Protection degree to DIN EN60529	IP65 with mating connectors
Duty factor	Continuous rating (ED=100%)

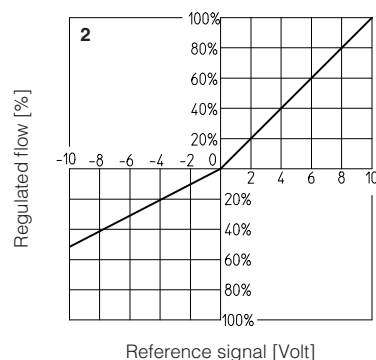
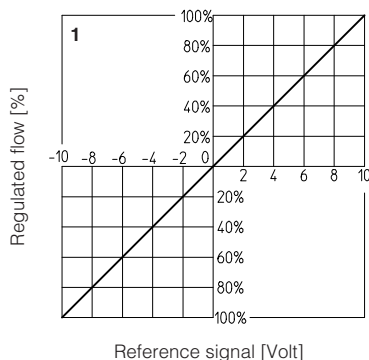
6 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid temperature	NBR seals (standard) = -20°C ÷ +80°C, with HFC hydraulic fluids = -20°C ÷ +50°C FKM seals (/PE option) = -20°C ÷ +80°C HNBR seals (/BT option) = -40°C ÷ +60°C, with HFC hydraulic fluids = -40°C ÷ +50°C		
Recommended viscosity	20÷100 mm ² /s - max allowed range 15 ÷ 380 mm ² /s		
Max fluid contamination level	normal operation	ISO4406 class 18/16/13 NAS1638 class 7	see also filter section at
	longer life	ISO4406 class 16/14/11 NAS1638 class 5	www.atos.com or KTF catalog
Hydraulic fluid	Suitable seals type	Classification	Ref. Standard
Mineral oils	NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524
Flame resistant without water	FKM	HFDU, HFDR	ISO 12922
Flame resistant with water	NBR, HNBR	HFC	

7 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

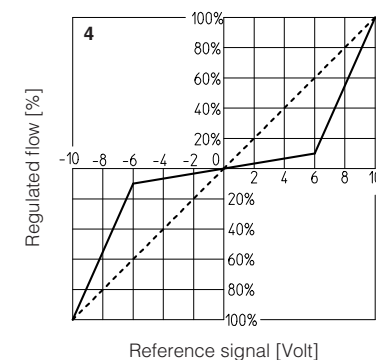
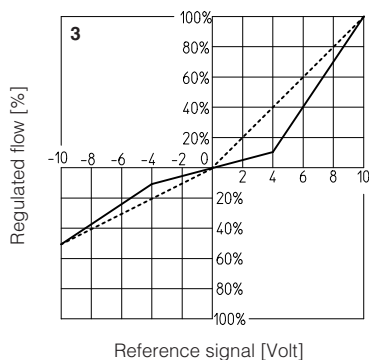
7.1 Regulation diagrams

- 1 = Linear spools L
- 2 = Differential - linear spool D7
- 3 = Differential non linear spool DT7
- 4 = Non linear spool T5 (only for DLHZO)
- 5 = Non linear spool T3 (only for DLKZOR) and T7
- 6 = Progressive spool V



T3, T5 and T7 spool types are specific for fine low flow control in the range from 0 to 60% (T5) and 0 to 40% (T3, T7) of max spool stroke. The non linear characteristics of the spool is compensated by the electronic driver, so the final valve regulation is resulting linear respect the reference signal (dotted line).

DT7 has the same characteristic of T7 but it is specific for applications with cylinders with area ratio 1:2



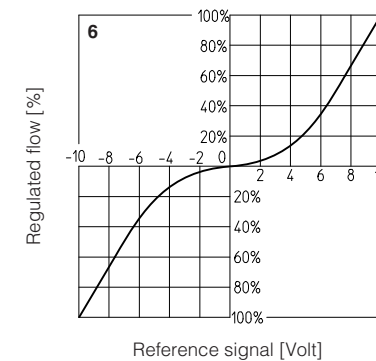
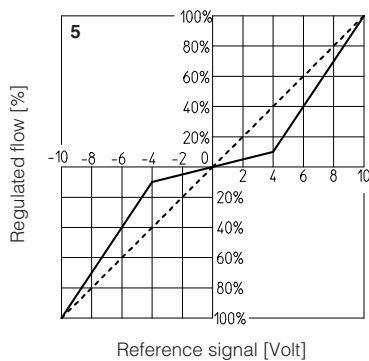
Note:
Hydraulic configuration vs. reference signal:

Standard:
Reference signal $\left. \begin{matrix} 0 \div +10 \text{ V} \\ 12 \div 20 \text{ mA} \end{matrix} \right\} P \rightarrow A / B \rightarrow T$

Reference signal $\left. \begin{matrix} 0 \div -10 \text{ V} \\ 12 \div 4 \text{ mA} \end{matrix} \right\} P \rightarrow B / A \rightarrow T$

option /B:
Reference signal $\left. \begin{matrix} 0 \div +10 \text{ V} \\ 12 \div 20 \text{ mA} \end{matrix} \right\} P \rightarrow B / A \rightarrow T$

Reference signal $\left. \begin{matrix} 0 \div -10 \text{ V} \\ 12 \div 4 \text{ mA} \end{matrix} \right\} P \rightarrow A / B \rightarrow T$



7.2 Flow / Δp diagrams

Stated at 100% of spool stroke

DLHZO:

1 = spool L7, T7, V7, D7, DT7

2 = spool L5, T5

3 = spool V3

4 = spool L3

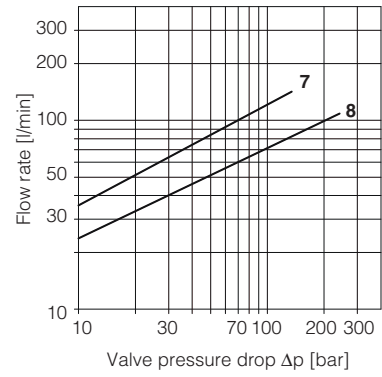
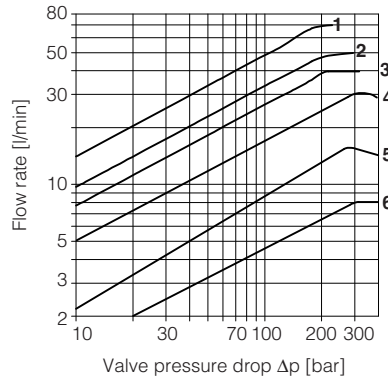
5 = spool L1, V1

6 = spool L0

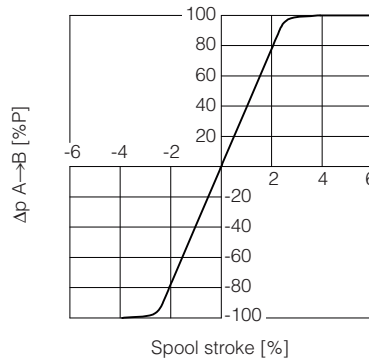
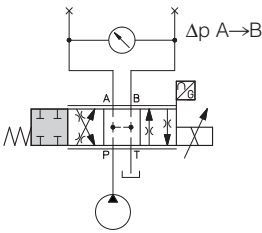
DLKZOR:

7 = spool L7, T7, V7, D7, DT7

8 = spool L3

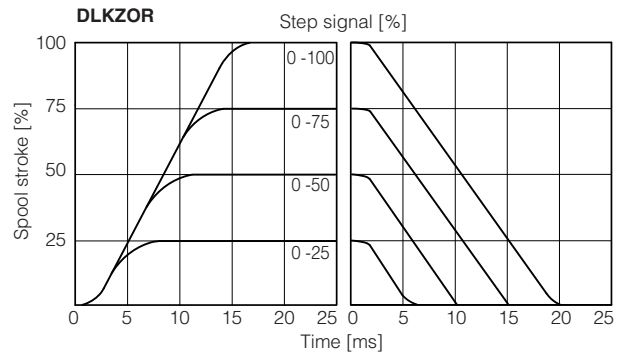
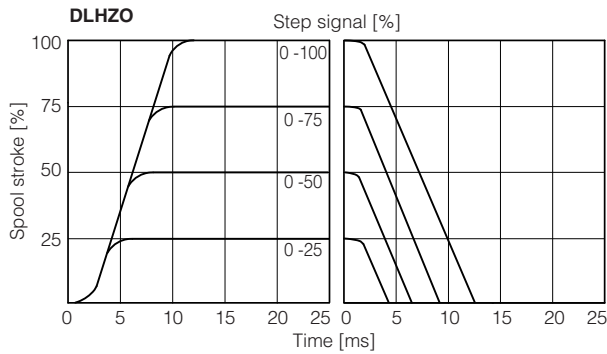


7.3 Pressure gain



7.4 Response time

The response times in below diagrams are measured at different steps of the reference input signal. They have to be considered as average values. For the valves with digital electronics the dynamics performances can be optimized by setting the internal software parameters.



7.5 Bode diagrams

Stated at nominal hydraulic conditions

DLHZO:

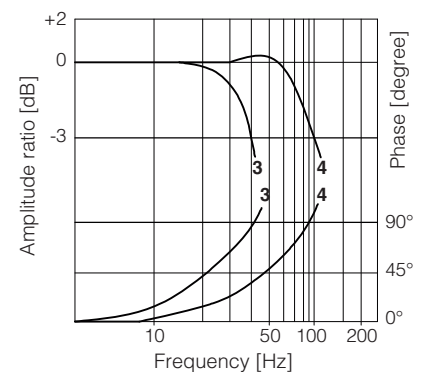
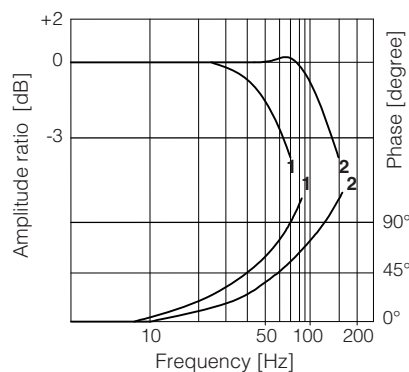
1 = $\pm 100\%$ nominal stroke

2 = $\pm 5\%$ nominal stroke

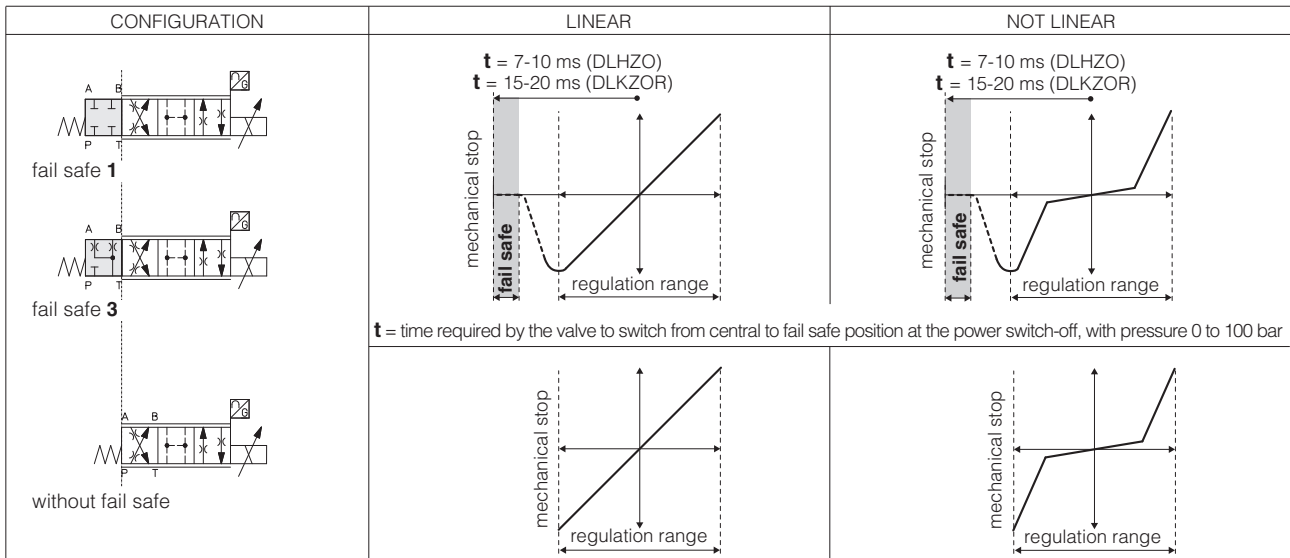
DLKZOR:

3 = $\pm 100\%$ nominal stroke

4 = $\pm 5\%$ nominal stroke



8 FAIL SAFE POSITION



Fail safe connections		P → A	P → B	A → T	B → T
Leakage [cm ³ /min] at P = 100 bar (1)	Fail safe 1	50	70	70	50
	Fail safe 3	50	70	-	-
Flow [l/min] (2)	Fail safe 3	DLHZO	-	15÷30	10÷20
		DLKZOR	-	40÷60	25÷40

(1) Referred to spool in fail safe position and 50°C oil temperature (2) Referred to spool in fail safe position at $\Delta p = 35$ bar per edge

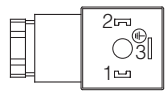
9 HYDRAULIC OPTIONS

B = Solenoid and position transducer at side of port A of the main stage. For hydraulic configuration vs reference signal, see 7.1

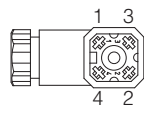
Y = This option is mandatory if the pressure in port T exceeds 210 bar.

10 ELECTRICAL CONNECTION

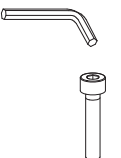

10.1 Solenoid connector - supplied with the valve

PIN	SIGNAL	TECHNICAL SPECIFICATION	Connector code 666
1	COIL	Power supply	
2	COIL	Power supply	
3	GND	Ground	

10.2 LVDT transducer connector - supplied with the valve

PIN	SIGNAL	TECHNICAL SPECIFICATION	Connector code 345
1	TR	Output signal	
2	VT-	Power supply -15Vdc	
3	VT+	Power supply +15Vdc	
4	GND	Ground	

11 FASTENING BOLTS AND SEALS

	DLHZO	DLKZOR
	<p>Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm</p>	<p>Fastening bolts: 4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm</p>
	<p>Seals: 4 OR 108; Diameter of ports A, B, P, T: $\varnothing 7,5$ mm (max) 1 OR 2025 Diameter of port Y: $\varnothing = 3,2$ mm (only for /Y option)</p>	<p>Seals: 5 OR 2050; Diameter of ports A, B, P, T: $\varnothing 11,2$ mm (max) 1 OR 108 Diameter of port Y: $\varnothing = 5$ mm (only for /Y option)</p>

12 INSTALLATION DIMENSIONS [mm]

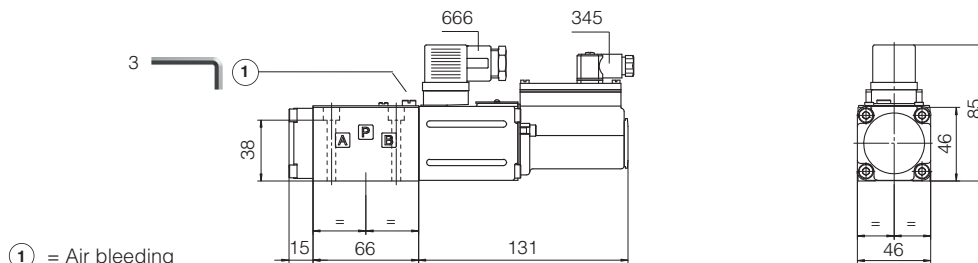
DLHZO-T

ISO 4401: 2005

Mounting surface: 4401-03-02-0-05 (see table P005)

(for /Y surface 4401-03-03-0-05 without X port)

Mass [kg]	
DLHZO	2,3



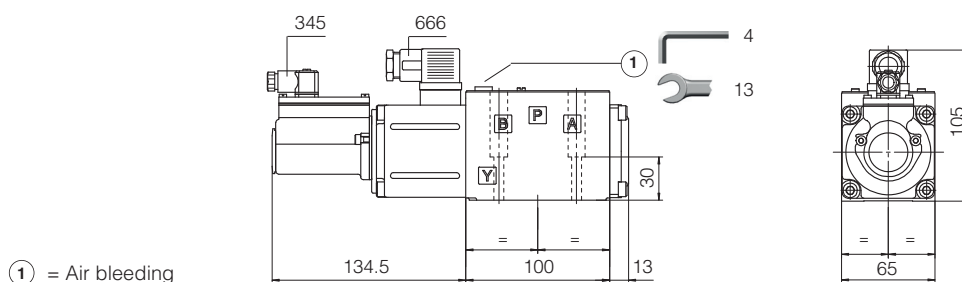
DLKZOR-T

ISO 4401: 2005

Mounting surface: 4401-05-04-0-05 (see table P005)

(for /Y surface 4401-05-05-0-05 without X port)

Mass [kg]	
DLKZOR	4,3



Note: for option /B the solenoid and the LVDT transducer are at side of port A

13 RELATED DOCUMENTATION

FS001	Basics for digital electrohydraulics	GS500	Programming tools
FS900	Operating and maintenance information for proportional valves	GS510	Fieldbus
GS230	E-BM-TEB digital driver	K800	Electric and electronic connectors
GS240	E-BM-TEZ digital driver	P005	Mounting surfaces for electrohydraulic valves
GS330	Z-BM-TEZ digital axis card		