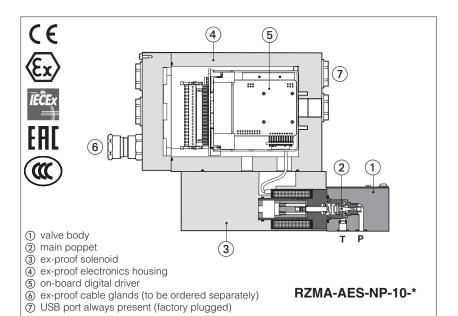


Ex-proof digital proportional relief valves

direct or piloted, with on-board driver and without transducer ATEX, IECEx, EAC, CCC



RZMA-AES, AGMZA-AES

Ex-proof digital proportional relief valves direct or piloted without transducer for pressure open loop controls.

They are equipped with ex-proof on-board digital driver and proportional solenoid certified for safe operations in hazardous environments with potentially explosive atmosphere.

• Multicertification ATEX, IECEx, EAC, CCC for gas group II 2G and dust category II 2D

The flameproof enclosure of on-board digital driver and solenoid, prevents the propagation of accidental internal sparks or fire to the external environment.

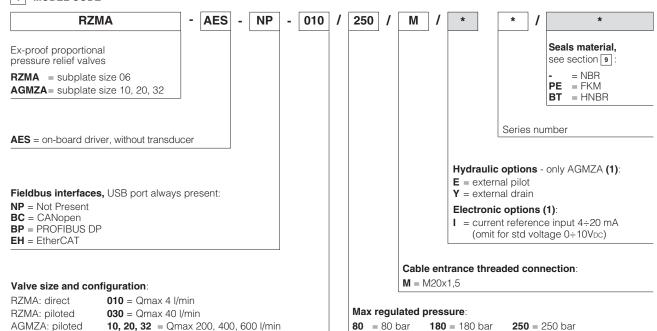
The driver and solenoid are also designed to limit the surface temperature within the classified limits.

RZMA, direct or piloted: Size: 06 -ISO 4401 Max flow: 4 and 40 I/min

AGMZA, piloted: Size: **10**, **20** and **32** -ISO 6264 Max flow: 200, 400 and 600 I/min

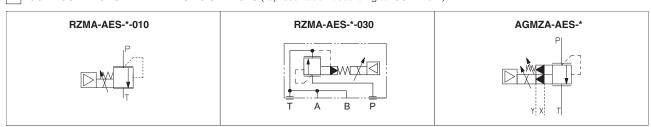
Max pressure: 250 bar

1 MODEL CODE



(1) Possible combined options: /EY, /EI, /YI

2 CONFIGURATIONS AND HYDRAULIC SYMBOLS (representation according to ISO 1219-1)



3 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

4 VALVE SETTINGS AND PROGRAMMING TOOLS

WARNING: the below operation must be performed in a safety area

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver (see table **GS003**). For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table **GS500**):

 E-SW-BASIC
 support:
 NP (USB)
 PS (Serial)
 IR (Infrared)

 E-SW-FIELDBUS
 support:
 BC (CANopen)
 BP (PROFIBUS DP)
 EH (EtherCAT)

 EW (POWERLINK)
 EI (EtherNet/IP)
 EP (PROFINET)

EW (POWERLINK) EI (EtherNet/IP) EP (PROFINET)

E-SW-*/PQ support: valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

 \triangle

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection



WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

5 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

6 GENERAL CHARACTERISTICS

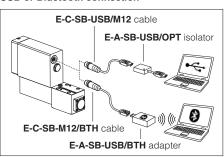
Assembly position	Any position					
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100					
MTTFd valves according to EN ISO 13849	RZMA-010 150 years, RZMA-030 and AGMZA 75 years, see technical table P007					
Ambient temperature range	Standard = -20° C ÷ $+60^{\circ}$ C /PE option = -20° C ÷ $+60^{\circ}$ C /BT option = -40° C ÷ $+60^{\circ}$ C					
Storage temperature range	Standard = $-20^{\circ}\text{C} \div +70^{\circ}\text{C}$ /PE option = $-20^{\circ}\text{C} \div +70^{\circ}\text{C}$ /BT option = $-40^{\circ}\text{C} \div +70^{\circ}\text{C}$					
Surface protection	Zinc coating with black passivation - salt spray test (EN ISO 9227) > 200 h					
Compliance	Explosion proof protection, see section 10 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"					
	RoHs Directive 2011/65/EU as last update by 2015/863/EU REACH Regulation (EC) n°1907/2006					

7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		RZ	AGMZA				
Size code		010	030	10	20	32	
Valve size		0	6	10	20	32	
Max regulated pressure	[bar]		80 180 250				
Min regulated pressure [bar]		see	see min. pressure / flow diagrams at sections [18] [19] [20]				
Max pressure at port P, A, B, X	[bar]		315				
Max pressure at port T, Y	[bar]	210					
Max flow	[l/min]	4	40	200	400	600	
Response time 0-100% step signal (depending on installation) (1) [ms]		≤80 ≤130 ≤145 ≤160				≤ 160	
Hysteresis [% of the max pressure]		≤1,5					
Linearity [% of the max pressure]		≤3					
Repeatability [% of the max pressur	e]		≤	2			

⁽¹⁾ Average response time value; the pressure variation in consequence of a modification of the reference input signal to the valve is affected by the stiffness of the hydraulic circuit: greater is the stiffness of the circuit, faster is the dynamic response

USB or Bluetooth connection



8 ELECTRICAL CHARACTERISTICS

Power supplies	1 1011111101	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)					
Max power consumption	35 W	35 W					
Analog input signals		Voltage: range ± 10 VDC (24 VMAX tollerant) Input impedance: Ri > 50 k Ω Current: range ± 20 mA Input impedance: Ri = 500 Ω					
Insulation class	H (180°) Due to the occ ISO 13732-1 and EN98			ils, the European standards			
Monitor outputs	Voltage: maximum ran	nge ± 5 Voc @ max	5 mA				
Enable input	Range: $0 \div 9$ VDC (OFF state), $15 \div 24$ VDC (ON state), $9 \div 15$ VDC (not accepted); Input impedance: Ri > $87k\Omega$						
Fault output	Output range: 0 ÷ 24 VDC (ON state \cong VL+ [logic power supply]; OFF state \cong 0 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)						
Alarms	Solenoid not connected current control monitor			ce signal, over/under temperature,			
Protection degree to DIN EN60529	IP66/67 with relevant c	able gland					
Duty factor	Continuous rating (ED=	=100%)					
Tropicalization	Tropical coating on ele	ctronics PCB					
Additional characteristics	Short circuit protection of solenoid current supply; current control by P.I.D. with rapid solenoid switching; protection against reverse polarity of power supply						
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)						
Communication interface	Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT EC 61158			
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX			

Note: a maximum time of 500 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	NBR seals (standard) = -20° C \div $+60^{\circ}$ C, with HFC hydraulic fluids = -20° C \div $+50^{\circ}$ C FKM seals (/PE option) = -20° C \div $+80^{\circ}$ C HNBR seals (/BT option) = -40° C \div $+60^{\circ}$ C, with HFC hydraulic fluids = -40° C \div $+50^{\circ}$ C				
Recommended viscosity		20 ÷100 mm²/s - max allowed ra	20 ÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1638 class 7		see also filter section at		
contamination level	longer life	ISO4406 class 16/14/11 NAS1	www.atos.com or KTF catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without wa	iter	FKM	HFDU, HFDR	ISO 12922		
Flame resistant with water	(1)	NBR, HNBR	HFC	1 130 12922		

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

- -max operating pressure = 210 bar
- -max fluid temperature = 50°C

10 CERTIFICATION DATA

Valve type		RZMA, AGMZA				
Certifications	Multicertification Group II					
	ATEX IECEX EAC CCC					
Solenoid certified code		OZA-AE	ES			
Type examination certificate (1)	ATEX: TUV IT 18 ATEX 068 >	• ATEX: TUV IT 18 ATEX 068 X • EAC: RU C - IT.A X 38.B.00425/21				
	• IECEx: IECEx TPS 19.0004X • CCC: 2021322307004057			057		
Method of protection	• ATEX Ex II 2G Ex db IIC T6/T5/T4 Gb; Ex II 2D Ex tb IIIC T85°C/T100°C/T135°C Db • IECEX Ex db IIC T6/T5/T4 Gb Ex tb IIIC T85°C/T100°C/T135°C Db • CCC Ex d IIC T6/T5/T4 Gb; Ex tb IIIC T85°C/T100°C/T135°C Db					
Temperature class	Т6	T5			T4	
Surface temperature	≤ 85 °C	≤ 100 °C			≤ 135 °C	
Ambient temperature (2)	-40 ÷ +40 °C		-40 ÷ +70 °C			
Applicable Standards	EN 60079-0: 2012+A11:2013 EN 60079-31:2014 IEC 60079-0:2017 IEC 60079-31:2013 EN 60079-1:2014				IEC 60079-31:2013	
Cable entrance: threaded connection		M = M20x1,5				

- (1) The type examination certificates can be downloaded from www.atos.com
- (2) The driver and solenoids are certified for minimum ambient temperature -40°C. In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

Power supply and signals: section of wire = 1,0 mm²

Grounding: section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	T4	135 °C	110 °C

12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table KX600

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

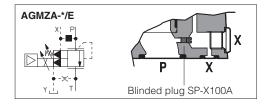
13 HYDRAULIC OPTIONS - only for AGMZA

E = External pilot option to be selected when the pilot pressure is supplied from a different line respect to the P main line.

With option E the internal connection between port P and X of the valve is plugged. The pilot pressure must be connected to the X port available on the valve's mounting surface or on main body (threaded pipe connection G $\frac{1}{4}$ ").

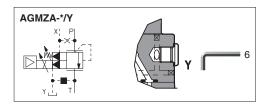
Y = The external drain is mandatory in case the main line T is subjected to pressure peaks or it is pressurized.

The Y drain port has a threaded connection G 1/4" available on the pilot stage body.



14 ELECTRONIC OPTIONS

I = It provides 4 ÷ 20 mA current reference signal, instead of the standard 0 ÷ 10 Vbc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vbc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.



15 POSSIBLE COMBINED OPTIONS

/EY, /EI, /YI

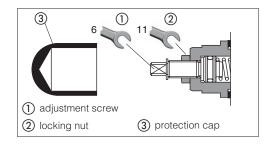
16 MECHANICAL PRESSURE LIMITER - only for AGMZA

The AGMZA are provided with mechanical pressure limiter acting as protection against overpressure. For safety reasons the factory setting of the mechanical pressure limiter is fully unloaded (min pressure).

At the first commissioning it must be set at a value lightly higher than the max pressure regulated with the proportional control.

For the pressure setting of the mechanical pressure limiter, proceed according to following steps:

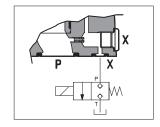
- apply the max reference input signal to the valve's driver. The system pressure will not increase until the mechanical pressure limiter remains unloaded.
- turn clockwise the adjustment screw ① until the system pressure will increase up to a stable value corresponding to the pressure setpoint at max reference input signal.
- turn clockwise the adjustment screw ① of additional 1 or 2 turns to ensure that the mechanical pressure limiter remains closed during the proportional valve working.



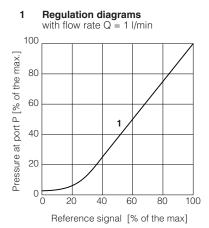
17 REMOTE PRESSURE UNLOADING - only for AGMZA

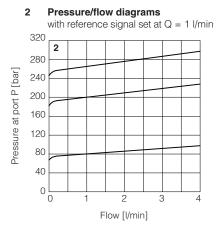
The \mathbf{P} main line can be remotely unloaded by connecting the valve X port to a solenoid valve as shown in the below scheme (venting valve).

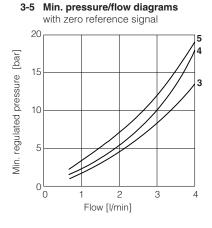
This function can be used in emergency to unload the system pressure by-passing the proportional control.



18 DIAGRAMS RZMA-010 (based on mineral oil ISO VG 46 at 50 °C)





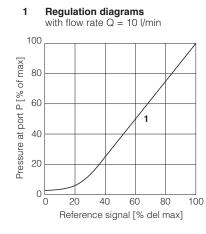


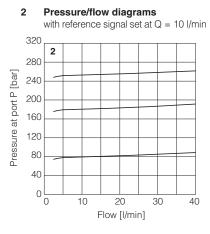
3 = RZMA/80

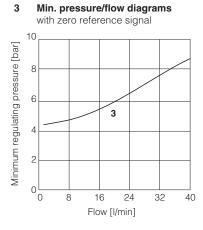
4 = RZMA/180

Note: the presence of counter pressure at port T can affect the pressure regulation and the minimum pressure 5 = RZMA/250

19 DIAGRAMS RZMA-030 (based on mineral oil ISO VG 46 at 50 °C)



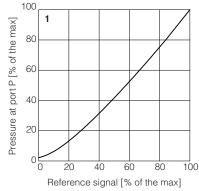


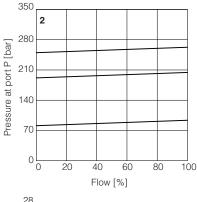


Note: the presence of counter pressure at port T can affect the pressure regulation and the minimum pressure

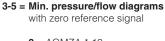
20 DIAGRAMS AGMZA (based on mineral oil ISO VG 46 at 50 °C)

1 = Regulation diagrams with flow rate Q = 50 l/min



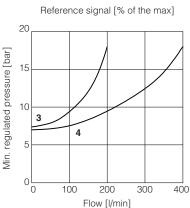


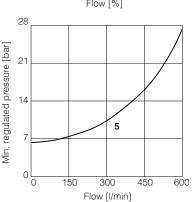
2 = Pressure/flow diagrams with reference signal set at Q = 50 l/min



3 = AGMZA-*-10 **4 =** AGMZA-*-20

5 = AGMZA-*-32





21 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, EN-982).

21.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

21.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

21.3 Flow reference input signal (INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are $0 \div 10$ VDC for standard and $4 \div 20$ mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDC.

21.4 Monitor output signal (MONITOR)

The driver generates an analog output signal (MONITOR) proportional to the actual coil current of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference).

Monitor output signal is factory preset according to selected valve code, default settings is 0 ÷ 5 VDC (1V = 1A).

Output signal can be reconfigured via software, within a maximum range of ±5 VDC.

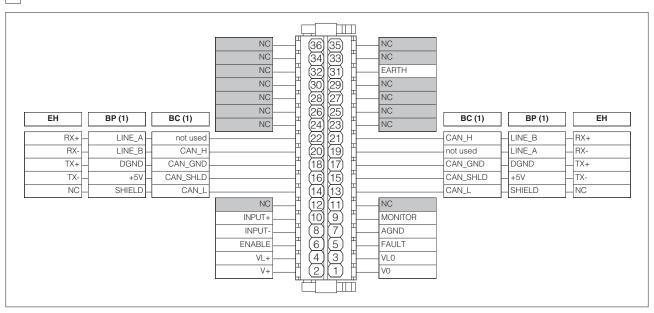
21.5 Enable input signal (ENABLE)

To enable the driver, supply a 24 Vpc on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

21.6 Fault output signal (FAULT)

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

2 TERMINAL BOARD OVERVIEW



23 ELECTRONIC CONNECTIONS

23.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vpc	Gnd - power supply
	2	V+	Power supply 24 Vpc	Input - power supply
	3	VL0	Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vpc for driver's logic and communication	Input - power supply
	5 FAULT 6 ENABLE 7 AGND		Fault (0 Vpc) or normal working (24 Vpc), referred to VL0	Output - on/off signal
Λ			Enable (24 VDC) or disable (0 VDC) the driver, referred to VL0	Input - on/off signal
			Analog ground	Gnd - analog signal
	8	INPUT-	Negative reference input signal for INPUT+	Input - analog signal
			Monitor output signal: ±5 Vpc maximum range, referred to AGND Default is: ±5 Vpc	Output - analog signal Software selectable
	10	INPUT+	Reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

23.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply	1 - 2	
	2	ID	Identification	[5]	
B	3	GND_USB	Signal zero data line		
	4	D-	Data line -	(famala)	
	5	D+	Data line +	(female)	

23.3 BC fieldbus execution connections

	CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
		14	CAN_L	Bus line (low)
		16	CAN_SHLD	Shield
	(;1]	18	CAN_GND	Signal zero data line
	•	20	CAN_H	Bus line (high)
		22	not used	Pass-through connection (1)

(1) Pin 19 and 22 can	be fed with external	+5V supply of CAN interface

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	CAN_L	Bus line (low)
	15	CAN_SHLD	Shield
(;2	17	CAN_GND	Signal zero data line
	19	not used	Pass-through connection (1)
	21	CAN_H	Bus line (high)

23.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
~ 4	16	+5V	Power supply
() 1	18	DGND	Data line and termination signal zero
O .	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

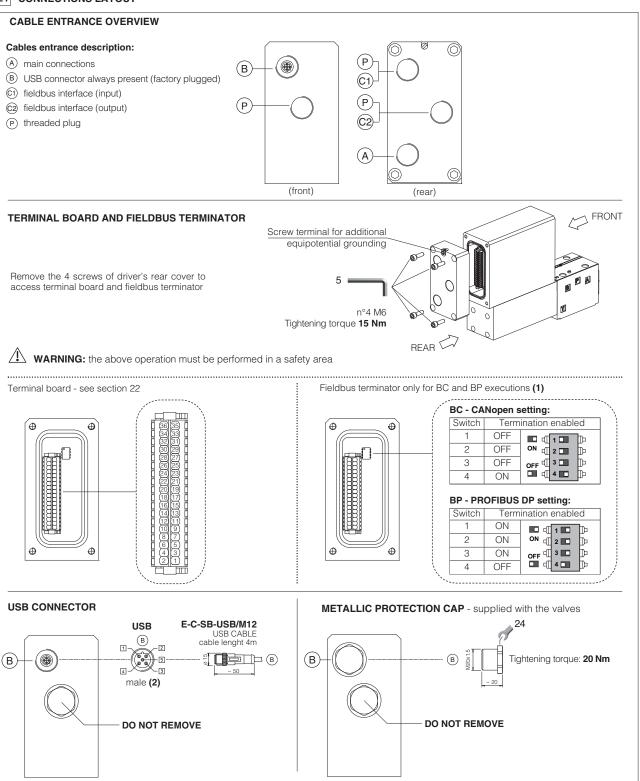
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
(;2	17	DGND	Data line and termination signal zero
<u> </u>	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

23.5 EH fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
~ 4	16	TX-	Transmitter
() 1	18	TX+	Transmitter
O .	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	TX-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

24 CONNECTIONS LAYOUT



- (1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF
- (2) Pin layout always referred to driver's view

${\bf 24.1~Cable~glands~and~threaded~plug}$ - see tech table ${\bf KX800}$

Communication	To be ordered separately		ered separately		Cable entrance	
interfaces		gland entrance		ed plug entrance	overview	Notes
NP	1	А	none	none	(P) (A)	Cable entrance P are factory plugged Cable entrance A is open for costumers
BC, BP, EH "via stub" connection	2	C1	1	C2		Cable entrance A, C1, C2 are open for costumers
BC, BP, EH "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers

25 FASTENING BOLTS AND SEALS

25.1 RZMA valves

	RZMA-AES-*-010	RZMA-AES-*-030
	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm	Fastening bolts: 4 socket head screws M5x50 class 12.9 Tightening torque = 8 Nm
0	Seals: 2 OR 108 Diameter of ports P, T: Ø 5 mm	Seals: 4 OR 108 Diameter of ports P, T: Ø 7,5 mm

25.2 AGMZA valves

	AGMZA-AES-*-10	AGMZA-AES-*-20	AGMZA-AES-*-32
	Fastening bolts:	Fastening bolts:	Fastening bolts:
	4 socket head screws M12x35 class 12.9	4 socket head screws M16x50 class 12.9	4 socket head screws M20x60 class 12.9
	Tightening torque = 125 Nm	Tightening torque = 300 Nm	Tightening torque = 600 Nm
	Seals:	Seals:	Seals:
	2 OR 123	2 OR 4112	2 OR 4131
()	Diameter of ports P, T: Ø 14 mm	Diameter of ports P, T: Ø 24 mm	Diameter of ports P, T: Ø 28 mm
	1 OR 109/70	1 OR 109/70	1 OR 109/70
	Diameter of port X: Ø 3,2 mm	Diameter of port X: Ø 3,2 mm	Diameter of port X: Ø 3,2 mm

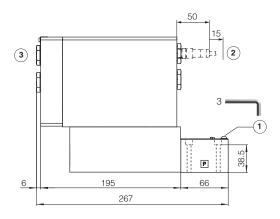
RZMA-AES-*-010

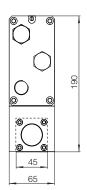
ISO 4401: 2005

Mounting surface: 4401-03-02-0-05 (see table P005)

(without ports A and B)

Mass [kg]
RZMA-AES-*-010	8





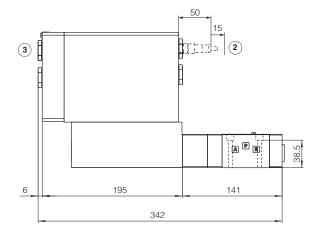
RZMA-AES-*-030

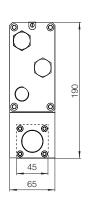
ISO 4401: 2005

Mounting surface: 4401-03-02-0-05 (see table P005)

(ports A and B connected to port T)

Mass [kg]
RZMA-AES-*-030	9





- \bigcirc = Air bleed off
- $(\mathbf{2})$ = Space to remove the USB connector
- (3) = The dimensions of cable glands must be considered (see tech table **KX800**)

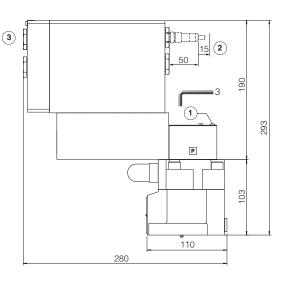
AGMZA-AES-*-10

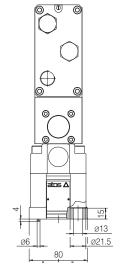
ISO 6264: 2007

Mounting surface: 6264-06-09-1-97

(see table P005)

Mass [kg]
AGMZA-AES-*-10	11,6

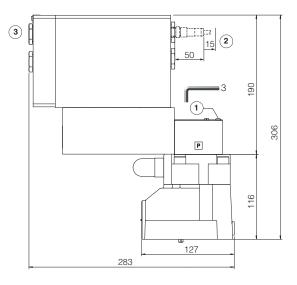


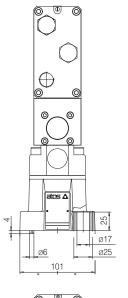


AGMZA-AES-*-20

ISO 6264: 2007 Mounting surface: 6264-08-13-1-97 (see table P005)

Mass [kg]
AGMZA-AES-*-20	12,8





AGMZA-AES-*-32

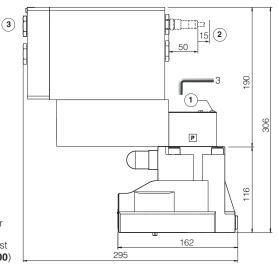
ISO 6264: 2007

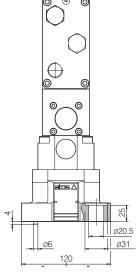
Mounting surface: 6264-10-17-1-97

(see table P005)

Mass [kg]
AGMZA-AFS-*-32	14.8

- 1 = Air bleed off
- (2) = Space to remove the USB connector
- (3) = The dimensions of cable glands must be considered (see tech table **KX800**)





28 RELATED DOCUMENTATION

X010 Basics for electrohydraulics in hazardous environments

X020 Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, CCC, PESO

FX900 Operating and manintenance information for ex-proof proportional valves

GS500 Programming tools

GS510 Fieldbus

P005

KX800 Cable glands for ex-proof valves

Mounting surfaces for electrohydraulic valves