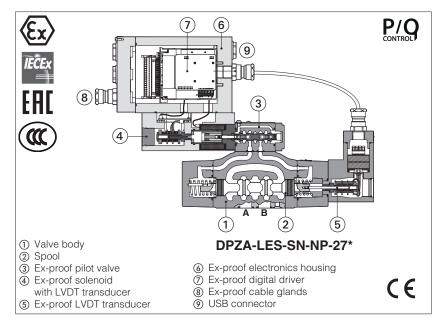


Ex-proof digital proportional directional valves high performance

piloted, with on-board driver, two LVDT transducers and positive spool overlap - ATEX, IECEx, EAC, CCC



DPZA-LES

Ex-proof digital high performances proportional valves, piloted with two LVDT position transducers (pilot valve and main stage) and positive spool overlap for best dynamics in directional controls and not compensated flow regulations.

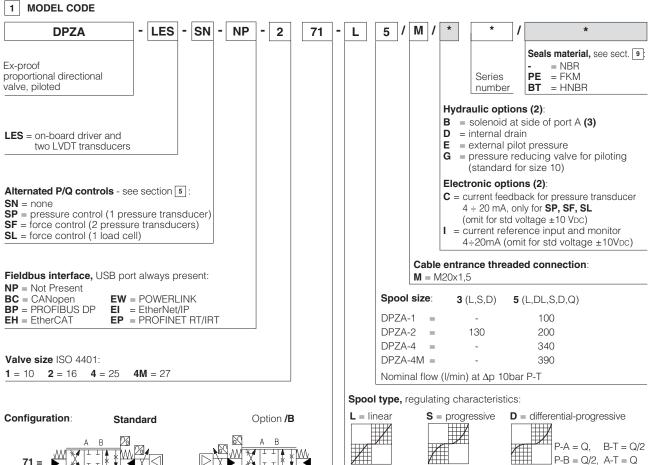
They are equipped with ex-proof on-board digital driver, LVDT transducer and proportional solenoid certified for safe operations in hazardous environments with potentially explosive atmosphere.

• Multicertification ATEX, IECEx, EAC, CCC for gas group II 2G and dust category II 2D

The flameproof enclosure of on-board digital driver, solenoid and trasducers, prevents the propagation of accidental internal sparks or fire to the external environment.

The driver and solenoid are also designed to limit the surface temperature within the classified limits

Size: 10 ÷ 27 - ISO 4401 Max flow: 180 ÷ 800 I/min Max pressure: 350 bar



(1) Spool type Q is available only with configuration 73 and 73/B

(2) For possible combined options, see section 15

Q = for P/Q controls (1)

(3) In standard configuration the solenoid with on-board digital driver and position transducer are at side A of main stage (side B of pilot valve)

DL = differential-linear

P-A = Q, B-T = Q/2P-B = Q/2. A-T = Q

2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-* programming software.

VALVE SETTINGS AND PROGRAMMING TOOLS



WARNING: the below operation must be performed in a safety area

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB port to the digital driver.

For fieldbus versions, the software permits valve's parameterization through USB port also if the driver is connected to the central machine unit via fieldbus.

The software is available in different versions according to the driver's options (see table GS500):

 E-SW-BASIC
 support
 NP (USB)
 PS (Serial)
 IR (Infrared)

 E-SW-FIELDBUS
 support
 BC (CANopen)
 BP (PROFIBUS DP)
 EH (EtherCAT)

 E-SW-*/PQ
 support
 EW (POWERLINK)
 EI (EtherNet/IP)
 EP (PROFINET)

 E-SW-*/PQ
 support
 valves with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

 $\overline{}$

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection



WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

5 ALTERNATED P/Q CONTROLS - see tech. table FX500

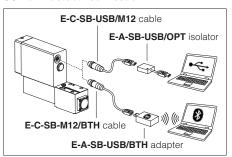
 S^* options add the closed loop control of pressure (SP) or force (SF and SL) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions.

An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP, 2 pressure transducers for SF or 1 load cell for SL). The alternated pressure control (SP) is possible only for specific installation conditions.

6 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index,	Ra ≤0,8 recommended Ra 0,4 - fl	atness ratio 0,01/100		
MTTFd valves according to EN ISO 13849	75 years, see technical table f	2007			
Ambient temperature range Standard = $-20^{\circ}\text{C} \div +60^{\circ}\text{C}$ /PE option = $-20^{\circ}\text{C} \div +60^{\circ}\text{C}$ /BT option			/BT option = -40° C ÷ $+60^{\circ}$ C		
Storage temperature range	Standard = -20° C ÷ $+70^{\circ}$ C	/PE option = -20° C ÷ $+70^{\circ}$ C	/BT option = -40° C ÷ $+70^{\circ}$ C		
Surface protection	Zinc coating with black passivation				
Corrosion resistance	Salt spay test (EN ISO 9227) >	> 200 h			
Compliance	Explosion proof protection, see section 11 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as REACH Regulation (EC) n°190				

USB or Bluetooth connection



7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Valve model		DPZA-*-1	DPZ	ZA-*-2	DPZA-*-4	DPZA-*-4M
Pressure limits	[bar]	pc	orts P, A, B, X = 35	$\mathbf{T} = 250 \text{ (10 for)}$	option /D); $\mathbf{Y} = 10$);
Spool type		L5, DL5, S5, D5, Q5	L3, S3, D3	ı	_5, DL5, S5, D5, Q5	i
Nominal flow [I/min]						
	$\Delta p = 10 \text{ bar}$	100	130	200	340	390
Δp P-T	$\Delta p = 30 \text{ bar}$	160	220	350	590	670
	Max permissible flow	180	320	440	680	800
Δp max P-T	[bar]	50	60	60	60	60
Piloting pressure	[bar]	[bar] min. = 25; max = 350 (option /G advisable for pilot pressure > 150 b			50 bar)	
Piloting volume	[cm ³]	1,4	3	3,7	9,0	11,3
Piloting flow (1)	[l/min]	1,7	3	3,7	6,8	8
Leakage	Pilot [cm³/min]	100/300	100	0/300	200/500	200/600
(2)	Main stage [I/min]	0,15/0,5	0,2	2/0,6	0,3/1,0	0,3/1,0
Response time (1)	[ms]	≤ 55 ≤ 65		≤ 85	≤ 90	
Hysteresis		≤ 0,1 [% of max regulation]				
Repeatability		± 0,1 [% of max regulation]				
Thermal drift			zero point c	lisplacement < 1% a	t ΔT = 40°C	

^{(1) 0 ÷100 %} step signal and pilot pressure 100 bar

8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal Rectified and filtered	Nominal : +24 VDC Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)				
Max power consumption	35 W	35 W				
Analog input signals		Voltage: range ± 10 VDC (24 VMAX tollerant)				
Insulation class		ccuring surface tempera 82 must be taken into a		ils, the European standards		
Monitor outputs		oltage ±10 VDC @ ma urrent ±20 mA @ ma	ax 5 mA x 500 Ω load resistance			
Enable input	Range: $0 \div 5 \text{ VDC}$ (OFF state), $9 \div 24 \text{ VDC}$ (ON state), $5 \div 9 \text{ VDC}$ (not accepted); Input impedance: Ri > 10 ks					
Fault output	Output range: 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)					
Pressure/force transducer power supply (only for SP, SF, SL)	+24VDC @ max 100 mA (E-ATRA-7 see tech table GX800)					
Alarms		Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature, valve spool transducer malfunctions				
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland				
Duty factor	Continuous rating (ED	=100%)				
Tropicalization	Tropical coating on ele	ectronics PCB				
Additional characteristics			; spool position control (SN against reverse polarity of	N) or pressure/force control (SP, SF, SL) fower supply		
Electromagnetic compatibility (EMC)						
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158		
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX		

Note: a maximum time of 800 ms (depending on communication type) have be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

Seals, recommended fluid	temperature	FKM seals (/PE option) = -20°C	- +60°C, with HFC hydraulic fluid: ÷ +80°C C ÷ +60°C, with HFC hydraulic flu		
Recommended viscosity		20 ÷100 mm²/s - max allowed range 15 ÷ 380 mm²/s			
Max fluid normal operation		ISO4406 class 18/16/13 NAS1	638 class 7	see also filter section at	
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	www.atos.com or KTF catalog	
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, HNBR	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM	HFDU, HFDR	ISO 12922	
Flame resistant with water	(1)	NBR, HNBR	HFC	130 12922	

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

(1) Performance limitations in case of flame resistant fluids with water:

-max operating pressure = 210 bar -max fluid temperature = 50°C

⁽²⁾ at P = 100/350 bar

10 CERTIFICATION DATA

Valve type	DPZA					
Certifications	Multicertification Group II ATEX IECEX EAC CCC					
Solenoid, transducer	Solenoid	Solenoid Transducer				
Solenoid and transducer certified code	OZA-LES			ETHA-4/*		
Type examination certificate (1)	• ATEX: TUV IT 18 ATEX 068 X • IECEx: IECEx TPS 19.0004X • EAC:RU C - IT.AX38.B.00425/21 • CCC: 2021322307004057 • ATEX: CESI 02 ATEX • IECEx: IECEx CES 12 • EAC:RU C - IT.AX38.B. • CCC: 2021322315003			CES 12.006X .A X 38.B.00425/21		
Method of protection	ATEX					
Temperature class	Т6	T:	5	T4		
Surface temperature	≤ 85 °C	≤ 100	O°C	≤ 135 °C		
Ambient temperature (2)	-40 ÷ +40 °C	-40 ÷ +	-55 °C	-40 ÷ +70 °C		
Applicable Standards	EN 60079-0 IEC 60079-0		0079-1 0079-31	EN 60079-31 IEC 60079-1		
Cable entrance: threaded connection		$\mathbf{M} = M_2$	20x1,5			

- (1) The type examination certificates can be downloaded from www.atos.com
- (2) The driver and solenoids are certified for minimum ambient temperature -40°C. In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

MARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification.

11 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm² Grounding: section of external ground wire = 4 mm²

11.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	T4	135 °C	110 °C

12 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table **KX800**

Note: a Loctite sealant type 545, should be used on the cable gland entry threads

13 HYDRAULIC OPTIONS

- Solenoid, integral electronics and position transducer at side of port B of the main stage
- D and E = Pilot and drain configuration can be modified as shown in section [21].

 The valve's standard configuration provides internal pilot and external drain.

 For different pilot / drain configuration select:

Option /D Internal drain.

Option /E External pilot (through port X).

G = Pressure reducing valve installed between pilot valve and main body with fixed setting:

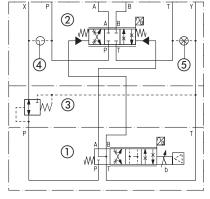
DPZA-2 = 28 bar

DPZA-1, -4 and -4M = 40 bar

It is advisable for valves with internal pilot in case of system pressure higher than 150 bar.

Pressure reducing valve is standard for DPZA-1, for other sizes add /G option.

FUNCTIONAL SCHEME - example of configuration 71



- ① Pilot valve
- 2 Main stage
- 3 Pressure reducing valve
- 4) Plug to be added for external pilot trough port X
- (5) Plug to be removed for internal drain through port T

14 ELECTRONIC OPTIONS

= It provides 4 ÷ 20 mA current reference signal, instead of the standard ±10 VDC.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

C = Only for SP, SF, SL

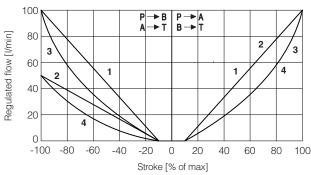
Option /C is available to connect pressure (force) transducers with 4 ÷ 20 mA current output signal, instead of the standard ±10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vpc or ±20 mA.

15 POSSIBLE COMBINED OPTIONS

Hydraulic options: all combination possible Electronics options: /Cl (only for SP, SF, SL)

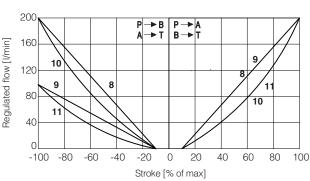
16 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

16.1 Regulation diagrams (values measure at Δp 10 bar P-T)



DPZA-1:

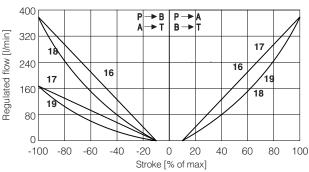
1=L5 **2** = DL5 3=S5 **4** = D5



DPZA-2:

9 = DL5 **8** = L5

10 = S5 **11** = D5



DPZA-4M:

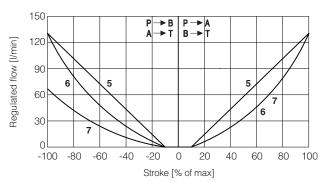
17 = DL5 **16** = L5

18 = S5 **19** = D5

Note: Hydraulic configuration vs. reference signal (standard and option /B)

Reference signal $\begin{array}{cc} 0 \div + 10 \text{ V} \\ 12 \div 20 \text{ mA} \end{array}$ $P \rightarrow A / B \rightarrow T$

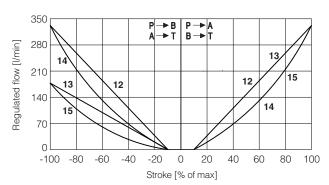
Reference signal $\begin{array}{cc} 0 \div - 10 \text{ V} \\ 12 \div 4 \text{ mA} \end{array} \right\} \text{ P} \rightarrow \text{B} / \text{A} \rightarrow \text{T}$



DPZA-2:

5=L3 **6** = S3

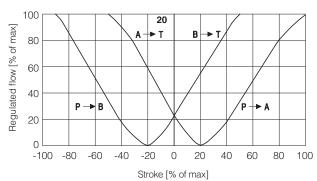
7=D3



DPZA-4:

13 = DL5 **12** = L5

14 = S5 **15** = D5



20 = Q5

20 = linear spool Q5

Q5 spool type is specific for alternate P/Q controls in combination with /S* option, (see tech. table FX500).

It allows to control the pressure in A port or B port and it provides a safety central position (A-T/B-T) to depressurize the actuator chambers.

The strong meter-in characteristic makes the spool suitable for both pressure control and motion regulations in several applications.

17 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

17.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

17.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000 μ F/40 V capacitance to single phase rectifiers or a 4700 μ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

17.3 Flow reference input signal (Q_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /l option.

Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog

17.4 Pressure or force reference input signal (F_INPUT+) - only SP, SF, SL

reference input signal can be used as on-off commands with input range 0 ÷ 24VDC.

Functionality of F_INPUT+ signal (pin 12), is used as reference for the driver pressure/force closed loop (see tech. table FX500). Reference input signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range $0 \div 24$ VDC.

17.5 Flow monitor output signal (Q_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are ± 10 VDC for standard and $4 \div 20$ mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ± 10 VDC or ± 20 mA.

17.6 Pressure or force monitor output signal (F_MONITOR) - only for SP, SF, SL

The driver generates an analog output signal proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

17.7 Enable input signal (ENABLE)

To enable the driver, supply a 24 VDC on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

17.8 Fault output signal (FAULT)

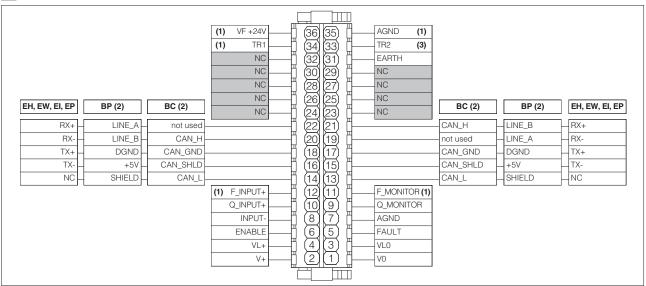
Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection

17.9 Remote pressure/force transducer input signal - only for SP, SF, SL

Analog remote pressure transducers or load cell can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see table FX500).

18 TERMINAL BOARD OVERVIEW



(1) connections available only SP, SF, SL

(2) For BC and BP executions the fieldbus connections have an internal pass-through connection

(3) connection available only SF

19 ELECTRONIC CONNECTIONS

19.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vpc	Gnd - power supply
	2	V+	Power supply 24 Voc	Input - power supply
	3	VL0	Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
A	8	INPUT-	Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
	9	Q_MONITOR	Flow monitor output signal: ±10 Vpc / ±20 mA maximum range, referred to AGND Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option	Output - analog signal Software selectable
	10	Q_INPUT+	Flow reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	11	F_MONITOR	Pressure/Force monitor output signal: ± 10 Vpc / ± 20 mA maximum range, referred to AGND (1) Defaults are: ± 10 Vpc for standard and 4 \div 20 mA for /I option	Output - analog signal Software selectable
	12	F_INPUT+	Pressure/Force reference input signal: ±10 Vpc / ±20 mA maximum range (1) Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /l option	Input - analog signal Software selectable
	31	EARTH	Internally connected to driver housing	

(1) Available only for SP, SF, SL

19.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply	1 2	
	2	ID	Identification	5	
\perp B	3	GND_USB	Signal zero data line		
	4 D- Data line -	Data line -	4 - (famala)		
	5	D+	Data line +	(female)	

19.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
~ 4	16	CAN_SHLD	Shield
(;1	18	CAN_GND	Signal zero data line
)	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

	CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
		13	CAN_L	Bus line (low)
		15	CAN_SHLD	Shield
	C2	17	CAN_GND	Signal zero data line
		19	not used	Pass-through connection (1)
		21	CAN_H	Bus line (high)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

19.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
~ 4	16	+5V	Power supply
(;1	18	DGND	Data line and termination signal zero
.	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
C2	15	+5V	Power supply
	17	DGND	Data line and termination signal zero
	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

19.5 EH, EW, EI, EP fieldbus execution connections

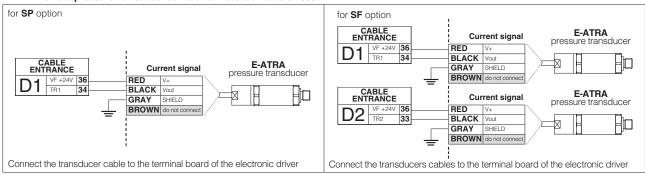
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
~ 4	16	TX-	Transmitter
(;1	18	TX+	Transmitter
O .	20	RX-	Receiver
(input)	22	RX+	Receiver

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	TX-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

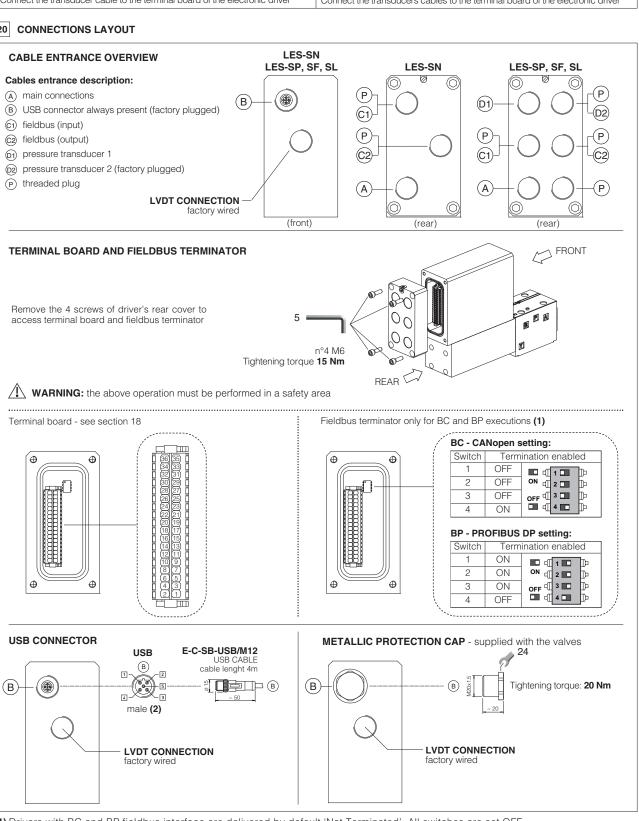
19.6 Remote pressure transducer connector - only for SP, SF, SL

CABLE ENTRANCES	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	SP, SL - Single Voltage	transducer (1) Current	SF - Double tr Voltage	ansducers (1) Current
D1	33	TR2	2nd signal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	/	/	Connect	Connect
וטו	34	TR1	1st ignal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal Software selectable	Connect	Connect	Connect	Connect
D2	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/	Connect	/
	36	VF +24V	Power supply +24Vpc	Output - power supply	Connect	Connect	Connect	Connect

E-ATRA remote pressure transducer connection - see tech table GX800



20 CONNECTIONS LAYOUT



- (1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF
- (2) Pin layout always referred to driver's view

20.1 Cable glands and threaded plug for LES-SN - see tech table $\ensuremath{\mathsf{KX800}}$

Communication	To be ordered separately				Cable entrance		
interfaces		gland entrance		ed plug entrance	overview	Notes	
NP	1	А	none	none	(P) (A)	Cable entrance A is open for costumers Cable entrance P are factory plugged	
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

20.2 Cable glands and threaded plug for LES-SP, SF, SL - see tech table KX800 $\,$

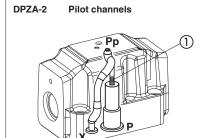
Communication	То	be ordere	ed separat	ely	Cable entrance	
interfaces		gland entrance	l	ed plug entrance	overview	Notes
NP	2 (SP) 3 (SF) 2 (SL)	D1 D2 A	none	none	50 P P 69 A P	Cable entrance A , D1 are open for costumers Cable entrance P , D2 are factory plugged (1)
BC, BP, EH, EW, EI, EP "via stub" connection	3 (SP) 4 (SF) 3 (SL)	D1 - D2 C1 A	1	C2	900 900 900 AP AP	Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P, D2 are factory plugged (1)
BC, BP, EH, EW, EI, EP "daisy chain" connection	4 (SP) 5 (SF) 4 (SL)	D1 - D2 C1 - C2 A	none	none	00 00 00 00 00 00 00 00	Cable entrance A, C1, C2, D1 are open for costumers Cable entrance P, D2 are factory plugged (1)

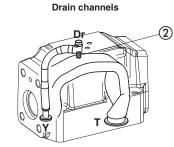
⁽¹⁾ Remove plug D2 for second transducer connection of SF version

21 PLUGS LOCATION FOR PILOT/DRAIN CHANNELS

Depending on the position of internal plugs, different pilot/drain configurations can be obtained as shown below. To modify the pilot/drain configuration, proper plugs must only be interchanged. The plugs have to be sealed using loctite 270. Standard valves configuration provides internal pilot and external drain

DPZA-1 Pilot channels Internal piloting: blinded plug SP-X300F ① in X; External piloting: blinded plug SP-X300F ② in Pp; Internal drain: blinded plug SP-X300F ④ in Dr. External drain: blinded plug SP-X300F ④ in Dr.



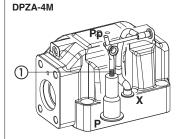


 Internal piloting:
 Without blinded plug SP-X300F ①;

 External piloting:
 Add blinded plug SP-X300F ①;

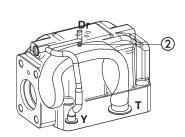
 Internal drain:
 Without blinded plug SP-X300F ②;

 External drain:
 Add blinded plug SP-X300F ②.



Pilot channels

DPZA-4



Drain channels

Internal piloting: Without blinded plug SP-X500F ①;
External piloting: Add blinded plug SP-X500F ①;
Internal drain: Without blinded plug SP-X300F ②;
External drain: Add blinded plug SP-X300F ②.

22 FASTENING BOLTS AND SEALS

Туре	Size	Fastening bolts	Seals
	1 = 10	4 socket head screws M6x40 class 12.9 Tightening torque = 15 Nm	5 OR 2050; Diameter of ports A, B, P, T: Ø 11 mm (max) 2 OR 108 Diameter of ports X, Y: Ø = 5 mm (max)
	• 10	4 socket head screws M10x50 class 12.9 Tightening torque = 70 Nm	4 OR 130; Diameter of ports A, B, P, T: Ø 20 mm (max)
DPZA	2 = 16	2 socket head screws M6x45 class 12.9 Tightening torque = 15 Nm	2 OR 2043 Diameter of ports X, Y: Ø = 7 mm (max)
DFZA	4 = 25	6 socket head screws M12x60 class 12.9	4 OR 4112; Diameter of ports A, B, P, T: Ø 24 mm (max)
	4 = 23	Tightening torque = 125 Nm	2 OR 3056 Diameter of ports X, Y: \emptyset = 7 mm (max)
	4M = 27	6 socket head screws M12x60 class 12.9 Tightening torque = 125 Nm	4 OR 3137; Diameter of ports A, B, P, T: Ø 32 mm (max)
	7W - 27		2 OR 3056 Diameter of ports X, Y: \emptyset = 7 mm (max)

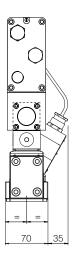
DPZA-LES-*-1

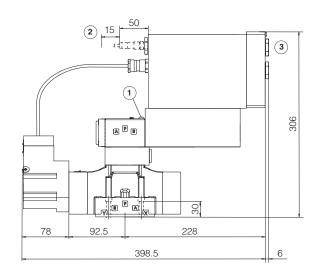
ISO 4401: 2005

Mounting surface: 4401-05-05-0-05

(see table P005)

Mass	s [kg]
DPZA-*-17*	9,5
Option /G	+0,9





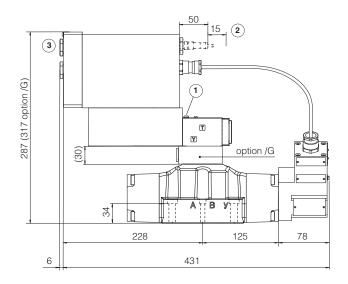
DPZA-LES-*-2

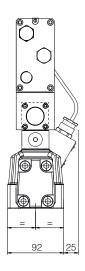
ISO 4401: 2005

Mounting surface: 4401-07-07-0-05

(see table P005)

Mass [kg]		
DPZA-*-27*	17,9	
Option /G	+0,9	





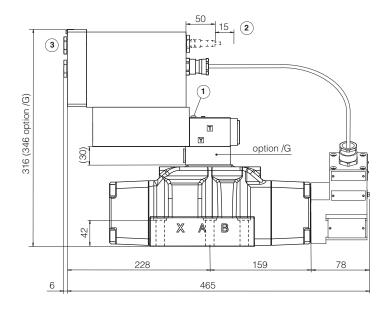
- 1 = Air bleeding
- $(\mathbf{2})$ = Space to remove the USB connector
- (3) = The dimensions of cable glands must be considered (see tech table **KX800**)

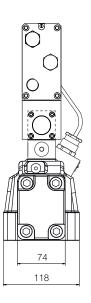
DPZA-LES-*-4 DPZA-LES-*-4M

ISO 4401: 2005

Mounting surface: 4401-08-08-0-05 (see table P005)

Mass	s [kg]
DPZA-*-4*	23,1
DPZA-*-4M*	23,1
Option /G	+0,9





- \bigcirc = Air bleeding
- (2) = Space to remove the USB connector
- (3) = The dimensions of cable glands must be considered (see tech table **KX800**)

24 RELATED DOCUMENTATION

X010 X020	Basics for electrohydraulics in hazardous environments Summary of Atos ex-proof components certified to ATEX, IECEx, EAC,	GS510 Fieldbus KX800 Cable glands for ex-proof valves	
	CCC, PESO	P005 Mounting surfaces for electrohydraulic valves	S
FX500	Ex-proof digital proportionals with P/Q control	E-MAN-RA-LES TES/LES user manual	
FX900	Operating and manintenance information for ex-proof proportional valves	E-MAN-RA-LES-S TES/LES with P/Q control user manu	ual
GS500	Programming tools		