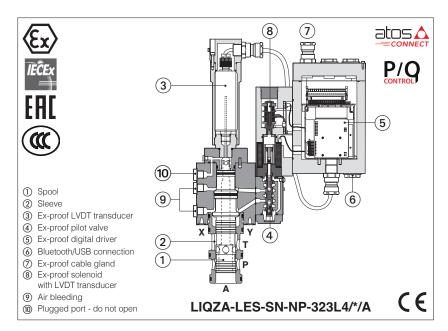


# Ex-proof digital servoproportional 3-way cartridges

piloted, with on-board driver and two LVDT transducers - ATEX, IECEx, EAC, CCC



#### LIQZA-LES

Ex-proof digital servoproportional 3-way cartridges, with two LVDT position transducers (pilot valve and main stage) for best accuracy in directional controls and in not compensated flow regulations.

They are equipped with ex-proof on-board digital driver, LVDT transducers and proportional solenoid certified for safe operations in hazardous environments with potentially explosive atmosphere.

 Multicertification ATEX, IECEx, EAC and CCC for gas group II 2G and dust category II 2D

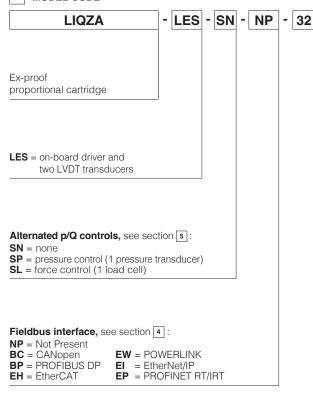
The flameproof enclosure of on-board digital driver, solenoid and transducer, prevents the propagation of accidental internal sparks or fire to the external environment.

The driver and solenoid are also designed to limit the surface temperature within the classified limits.

Size:  $25 \div 80$  - not ISO cavity Max flow:  $500 \div 5000$  l/min

Max pressure: 420 bar

#### 1 MODEL CODE



3 L4 M Seals material, see section 9: = NBR PE = FKM BT = NBR low temp. Series Hydraulic options (1): A = reversal hydraulic configuration of main spool: P-A in rest position Electronic options (1): C = current feedback for pressure transducer 4 ÷ 20 mA (only for LES-SP, SL) = current reference input and monitor 4 ÷ 20 mA Cable entrance threaded connection: M = M20X1,5Spool type, regulating characteristics, see section 16: L4 = linear

**Configuration:** 3 = 3 way

functional symbol: Standard

simplified symbol: Standard

(1) For possible combined options, see section 15

Valve size and nominal flow (I/min) at ∆p 5 bar:

**25** = 185 **32** = 330 **40** = 420

**50** = 780 **63** = 1250 **80** = 2100 option /A

#### 2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FX900** and in the user manuals included in the E-SW-SETUP programming software.

### 3 VALVE SETTINGS AND PROGRAMMING TOOLS - see tech. table GS500



WARNING: the below operation must be performed in a safety area!

#### 3.1 Atos CONNECT mobile App

Free downloadable App for smartphones and tablets which allows quick access to valve main functional parameters and basic diagnostic information via Bluetooth, thus avoiding physical cable connection and significantly reducing commissioning time.

Atos CONNECT supports Atos digital valve drivers equipped with E-A-BTH adapter or with built-in Bluetooth. It does not support valves with p/Q control or axis controls.













Bluetooth or USB connection

E-A-BTH adapter

E-C-SB-USB/M12 cable

mobile App

PC software

E-A-SB-USB/OPT isolator

#### 3.2 E-SW-SETUP PC software

Free downloadable software for PC allows to set all valve functional parameters and to access complete diagnostic information of digital valve drivers via Bluetooth/USB service port. Atos E-SW-SETUP PC software supports all Atos digital valve drivers and it is available at www.atos.com in MyAtos area.



**WARNING:** drivers **USB** port is not isolated! For E-C-SB-USB/M12 cable, the use of E-A-SB-USB/OPT isolator adapter is highly recommended for PC protection



 $\mbox{WARNING:}$  for the list of countries where the Bluetooth adapter has been approved, see tech. table  $\mbox{GS500}$ 

### 4 FIELDBUS - see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These executions allow to operate the valves through fieldbus or analog signals available on the terminal board.

#### 5 ALTERNATED p/Q CONTROLS - see tech. table FX500

S\* options add the closed loop control of pressure (SP) or force (SL) to the basic functions of proportional directional valves flow regulation. A dedicated algorithm alternates pressure (force) depending on the actual hydraulic system conditions.

An additional connector is available for transducers to be interfaced to the valve's driver (1 pressure transducer for SP or 1 load cell for SL). The alternated pressure control (SP) is possible only for specific installation conditions.

#### 6 GENERAL CHARACTERISTICS

Assembly position	Any position				
Subplate surface finishing to ISO 4401	Acceptable roughness index, Ra ≤0,8 recommended Ra 0,4 - flatness ratio 0,01/100				
MTTFd values according to EN ISO 13849	75 years, for further details see technical table P007				
Ambient temperature range	<b>Standard</b> = $-20^{\circ}\text{C} \div +60^{\circ}\text{C}$ /PE option = $-20^{\circ}\text{C} \div +60^{\circ}\text{C}$ /BT option = $-40^{\circ}\text{C} \div +60^{\circ}\text{C}$				
Storage temperature range	<b>Standard</b> = $-20^{\circ}\text{C} \div +70^{\circ}\text{C}$ /PE option = $-20^{\circ}\text{C} \div +70^{\circ}\text{C}$ /BT option = $-40^{\circ}\text{C} \div +70^{\circ}\text{C}$				
Surface protection	Zinc coating with black passivation				
Corrosion resistance	Salt spray test (ISO 9227) > 200 h				
Vibration resistance	See technical table GX004				
Compliance	Explosion proof protection, see section 11 -Flame proof enclosure "Ex d" -Dust ignition protection by enclosure "Ex t"				
	RoHs Directive 2011/65/EU as last update by 2015/863/EU REACH Regulation (EC) n°1907/2006				

#### 7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Size		25	32	40	50	63	80
Max regulated flow	[l/min]						
Δp P-A or A-T	at $\Delta p = 5$ bar at $\Delta p = 10$ bar	185 260	330 470	420 590	780 1100	1250 1750	2100 3000
Max permissible flow	•	500	850	1050	2000	3100	5000
Max pressure	[bar]		Ports F	P, A, T = <b>420</b>	X = 350	Y ≤ 10	
Nominal flow of pilot v	alve at Δp = 70 bar [l/min]	4	8	28	40	100	100
Leakage of pilot valve	e at P = 100 bar [I/min]	0,2	0,2	0,5	0,7	0,7	0,7
Piloting pressure	[bar]	min:	40% of system	pressure ma	ax 350 recor	nmended 140 ÷	160
Piloting volume	[cm³]	2,16	7,2	8,9	17,7	33,8	42,7
Piloting flow (1)	[l/min]	6,5	20	25	43	68	76
Response time (2)	[ms]	≤ 25	≤ 27	≤ 27	≤ 30	≤ 35	≤ 40
Hysteresis	[% of the max regulation]	≤0,1					
Repeatability	[% of the max regulation]	± 0,1					
Thermal drift			zero p	oint displaceme	ent < 1% at $\Delta T$ =	= 40°C	

(1) 0÷100% step signal

(2) With pilot pressure = 140 bar



#### 

The loss of the pilot pressure causes the undefined position of the main spool.

The sudden interruption of the power supply during the valve operation causes the immediate main spool opening  $A \to T$  or  $P \to A$  (for option /A). This could cause pressure surges in the hydraulic system or high decelerations which may lead to machine damages.

#### 8 ELECTRICAL CHARACTERISTICS

Power supplies	Nominal : +24 VDC   Rectified and filtered : VRMS = 20 ÷ 32 VMAX (ripple max 10 % VPP)					
Max power consumption	35 W					
Analog input signals	Voltage: range ±10 \ Current: range ±20 r	/DC (24 VMAX tolerant) mA	Input impedance Input impedance			
Insulation class		ccurring surface temper 82 must be taken into a		oils, the European standards		
Monitor outputs		oltage ±10 VDC @ ma urrent ±20 mA @ ma	ax 5 mA x 500 $\Omega$ load resistance			
Enable input	Range: 0 ÷ 5 VDC (OFF	state), 9 ÷ 24 VDC (ON s	state), 5 ÷ 9 VDC (not acc	epted); Input impedance: Ri > 10 k $\Omega$		
Fault output		VDC (ON state > [power age not allowed (e.g. du		ate < 1 V ) @ max 50 mA;		
Pressure/force transducer power supply (only for SP, SL)	+24VDC @ max 100 m	nA (E-ATRA-7 see tech	table <b>GX800</b> )			
Alarms		ed/short circuit, cable b r malfunctions, alarm hi		ence signal, over/under temperature,		
Protection degree to DIN EN60529	IP66/67 with relevant of	cable gland				
Duty factor	Continuous rating (ED	=100%)				
Tropicalization	Tropical coating on ele	ectronics PCB				
Additional characteristics			y; spool position control ( n against reverse polarity	(SN) or pressure/force control (SP, SL) of power supply		
Electromagnetic compatibility (EMC)	According to Directive 2014/30/UE (Immunity: EN 61000-6-2; Emission: EN 61000-6-3)					
Communication interface	USB Atos ASCII coding	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT, POWERLINK, EtherNet/IP, PROFINET IO RT / IRT EC 61158		
Communication physical layer	not insulated USB 2.0 + USB OTG	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX		

Note: a maximum time of 800 ms (depending on communication type) has to be considered between the driver energizing with the 24 VDC power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero

#### 9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

		NBR seals (standard) = $-20^{\circ}$ C $\div$ $+60^{\circ}$ C, with HFC hydraulic fluids = $-20^{\circ}$ C $\div$ $+50^{\circ}$ C			
Seals, recommended fluid	l temperature	FKM seals (/PE option) = -20°C	÷ +80°C		
		NBR low temp. (/BT option) = -4	10°C ÷ +60°C, with HFC hydraulic	$c \text{ fluids} = -20^{\circ}\text{C} \div +50^{\circ}\text{C}$	
Recommended viscosity		20 ÷100 mm²/s - max allowed ra	ange 15 ÷ 380 mm²/s		
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1	see also filter section at		
contamination level	longer life	ISO4406 class 16/14/11 NAS1	638 class 5	www.atos.com or KTF catalog	
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard	
Mineral oils		NBR, FKM, NBR low temp.	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524	
Flame resistant without water		FKM HFDU, HFDR		- ISO 12922	
Flame resistant with water	(1)	NBR, NBR low temp.	HFC	100 12922	

The ignition temperature of the hydraulic fluid must be 50°C higher than the max solenoid surface temperature

### (1) Performance limitations in case of flame resistant fluids with water:

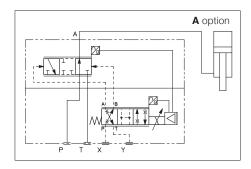
-max operating pressure = 210 bar -max fluid temperature = 50°C

#### 10 HYDRAULIC OPTIONS

A = The standard valve version provides the hydraulic configuration A-T of main spool in absence of electric power supply to the valve.

The option /A provides the reverse configuration P-A of main spool in absence of electric power supply to the valve.

This execution is particularly requested in vertical presses for safety reasons, because in case of electric power breakdown the P-A configuration of the main spool prevents the uncontrolled and dangerous downstroke of the press ram.



#### 11 ELECTRONIC OPTIONS

I = This option provides 4 ÷ 20 mA current reference and monitor signals, instead of the standard ±10 Vpc. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.

#### C = Only for SP, SL

This option is available to connect pressure (force) transducers with 4 ÷ 20 mA current output signal, instead of the standard 0 ÷ 10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDc or ±20 mA.

### 12 POSSIBLE COMBINED OPTIONS

For SN: /Al

For SP, SL: /AC, AI, /CI, /ACI

### 13 CERTIFICATION DATA

	5.11						
Components type	Pilot va	alve solenoid and LVDT tra	nsducer			LVDT main stage transducer	
Certifications		Multicertification Group	ATEX	IECEx	EAC	CCC	
Components Certified code		OZA-LES				ETHA-15	
Type examination certificate (1)	,	ATEX: TUV IT 18 ATEX 068 X					
		IECEx: IECEx TPS 19.000	4X			IECEx: IECEx TPS 16.0003X	
	E	AC:RU C - IT.A <b>X</b> 38.B.0042	25/21			EAC:RU C-IT.A <b>Ж</b> 38.B.00425/21	
		CCC: 202432230700632	1			CCC: 2024322315006312	
Method of protection	ATEX     EX II 2G EX db IIC T6/T5/T4 Gb     EX II 2D EX tb IIIC T85°C/T100°C/T135°C Db      EX II 2D EX tb IIIC T85°C/T100°C/T135°C Db      EAC:     1EX d IIC T6/T5/T4 Gb     EX tb IIIC T85°C/T100°C/T135°C Db X				ATEX EX II 2G EX db IIC T6 Gb EX II 2D EX tb IIIC T85°C Db EX I M2 EX db IMb  IECEX EX db IIC T6 Gb EX tb IIIC T85°C Db EX db IIC T85°C Db EX db IMb  EAC:  1EX d IIC T4/T3 Gb X EX tb IIIC T135°C/T200°C Db X  CCC EX db IIC T6 Gb EX tb IIIC T85°C Db		
Temperature class	T6 T5 T4		Т6				
Surface temperature	≤ 85 °C ≤ 100 °C ≤ 135		≤ 135 °C		≤85 °C		
Ambient temperature (2)	-40 ÷ +40 °C		С	-40 ÷ +70 °C			
Applicable Standards	EN 60079-0 EN 60079-31 IEC 60079-0 EN 60079-1				IEC 60079-31		
Cable entrance: threaded connection		M = M20x1,5				factory wired	

- (1) The type examinator certificates can be downloaded from www.atos.com
- (2) The driver solenoid and LVDT transducers are certified for minimum ambient temperature -40°C. In case the complete valve must withstand with minimum ambient temperature -40°C, select /BT in the model code.

WARNING: service work performed on the valve by the end users or not qualified personnel invalidates the certification

14 CABLE SPECIFICATION AND TEMPERATURE - Power supply and grounding cables have to comply with following characteristics:

Power supply and signals: section of wire = 1,0 mm<sup>2</sup> Grounding: section of external ground wire = 4 mm<sup>2</sup>

### 14.1 Cable temperature

The cable must be suitable for the working temperature as specified in the "safety instructions" delivered with the first supply of the products.

Max ambient temperature [°C]	Temperature class	Max surface temperature [°C]	Min. cable temperature [°C]
40 °C	T6	85 °C	80 °C
55 °C	T5	100 °C	90 °C
70 °C	T4	135 °C	110 °C

#### 15 CABLE GLANDS

Cable glands with threaded connections M20x1,5 for standard or armoured cables have to be ordered separately, see tech table KX800 Note: a Loctite sealant type 545, should be used on the cable gland entry threads

16 DIAGRAMS (based on mineral oil ISO VG 46 at 50 °C)

#### 16.1 Regulation diagrams, see note

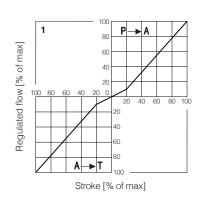
1 = LIQZA (all sizes)

Hydraulic configuration vs. reference signal:

standard option /A

 $12 \div 20 \text{ mA}$   $P \rightarrow A$ Reference signal 0 ÷+10 V

Reference signal 0 ÷-10 V  $4\div12 \text{ mA}$  A  $\rightarrow$  T P  $\rightarrow$  A



#### 17 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

#### 17.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

#### 17.2 Power supply for driver's logic and communication (VL+ and VL0)

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 3 and 4, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

#### 17.3 Flow reference input signal (Q\_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are  $\pm 10$  VDC for standard and  $4 \div 20$  mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDC or  $\pm 20$  mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range  $0 \div 24$ VDC.

#### 17.4 Pressure or force reference input signal (F\_INPUT+) - only SP, SL

Functionality of F\_INPUT+ signal (pin 12), is used as reference for the driver pressure/force closed loop (see tech. table FX500). Reference input signal is factory preset according to selected valve code, defaults are  $0 \div 10$  VDc for standard and  $4 \div 20$  mA for /I option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDc or  $\pm 20$  mA. Drivers with fieldbus interface can be software set to receive reference signal directly by the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range  $0 \div 24$ VDC.

#### 18.5 Flow monitor output signal (Q\_MONITOR)

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position).

Monitor output signal is factory preset according to selected valve code, defaults are ±10 VDC for standard and 4 ÷ 20 mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ± 20 mA.

# 17.6 Pressure or force monitor output signal (F\_MONITOR) - only for SP, SL

The driver generates an analog output signal proportional to alternated pressure/force control; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, force reference).

Monitor output signal is factory preset according to selected valve code, defaults are  $0 \div 10$  VDc for standard and  $4 \div 20$  mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDc or  $\pm 20$  mA.

#### 17.7 Enable input signal (ENABLE)

To enable the driver, supply a 24 Vpc on pin 6: Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

#### 17.8 Fault output signal (FAULT)

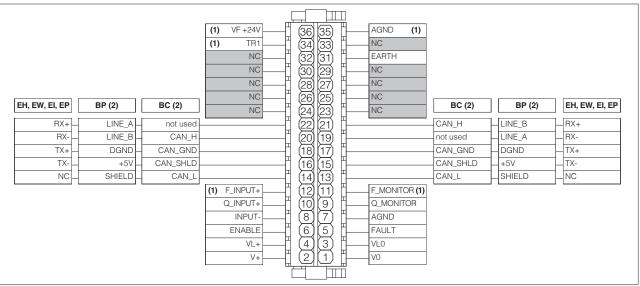
Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 Vpc, normal working corresponds to 24 Vpc. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

#### 17.9 Remote pressure/force transducer input signal - only for SP, SL

Analog remote pressure transducers or load cell can be directly connected to the driver.

Analog input signal is factory preset according to selected valve code, defaults are ±10 Vpc for standard and 4 ÷ 20 mA for /C option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 Vpc or ± 20 mA. Refer to pressure/force transducer characteristics to select the transducer type according to specific application requirements (see table FX500).

#### 18 TERMINAL BOARD OVERVIEW



(1) Connections available only SP, SL

# 19 ELECTRONIC CONNECTIONS

### 19.1 Main connections signals

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
	1	V0	Power supply 0 Vpc	Gnd - power supply
	2	V+	Power supply 24 Voc	Input - power supply
	3	VL0	Power supply 0 Vpc for driver's logic and communication	Gnd - power supply
	4	VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
	5	FAULT	Fault (0 Vbc) or normal working (24 Vbc), referred to VL0	Output - on/off signal
	6	ENABLE	Enable (24 Vpc) or disable (0 Vpc) the driver, referred to VL0	Input - on/off signal
	7	AGND	Analog ground	Gnd - analog signal
A	8	INPUT-	Negative reference input signal for Q_INPUT+ and F_INPUT+	Input - analog signal
	9	Q_MONITOR	Flow monitor output signal: ±10 Vbc / ±20 mA maximum range, referred to AGND Defaults are: ±10 Vbc for standard and 4 ÷ 20 mA for /l option	Output - analog signal <b>Software selectable</b>
	10	Q_INPUT+	Flow reference input signal: ±10 Vpc / ±20 mA maximum range Defaults are: ±10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal Software selectable
	11	F_MONITOR	Pressure/Force monitor output signal: $\pm 10$ Vpc / $\pm 20$ mA maximum range, referred to AGND (1) Defaults are: $0 \div 10$ Vpc for standard and $4 \div 20$ mA for /I option	Output - analog signal <b>Software selectable</b>
	12	F_INPUT+	Pressure/Force reference input signal: ±10 Vpc / ±20 mA maximum range (1) Defaults are: 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Input - analog signal <b>Software selectable</b>
	31	EARTH	Internally connected to driver housing	

(1) Available only for SP, SL

#### 19.2 USB connector - M12 - 5 pin always present

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	Driver view	B
	1	+5V_USB	Power supply	1-2	
_		ID	Identification	5	
B		GND_USB	Signal zero data line		
	4	D-	Data line -	4 -/ 3	
	5 <b>D+</b>	D+	Data line +	(female)	

#### 19.3 BC fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	CAN_L	Bus line (low)
•	16	CAN_SHLD	Shield
C1	18	CAN_GND	Signal zero data line
<b>O</b> 1	20	CAN_H	Bus line (high)
	22	not used	Pass-through connection (1)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	CAN_L	Bus line (low)
	15	CAN_SHLD	Shield
C2	17	CAN_GND	Signal zero data line
	19	not used	Pass-through connection (1)
	21	CAN_H	Bus line (high)

(1) Pin 19 and 22 can be fed with external +5V supply of CAN interface

# 19.4 BP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	SHIELD	
	16	+5V	Power supply
C1	18	DGND	Data line and termination signal zero
	20	LINE_B	Bus line (low)
	22	LINE_A	Bus line (high)

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	SHIELD	
	15	+5V	Power supply
C2	17	DGND	Data line and termination signal zero
OL.	19	LINE_A	Bus line (high)
	21	LINE_B	Bus line (low)

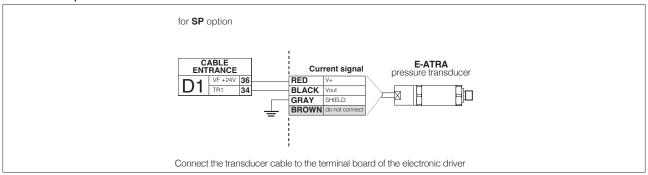
#### 19.5 EH, EW, EI, EP fieldbus execution connections

CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	14	NC	do not connect
	16	TX-	Transmitter
C1	18	TX+	Transmitter
	20	RX-	Receiver
(input)	22	RX+	Receiver

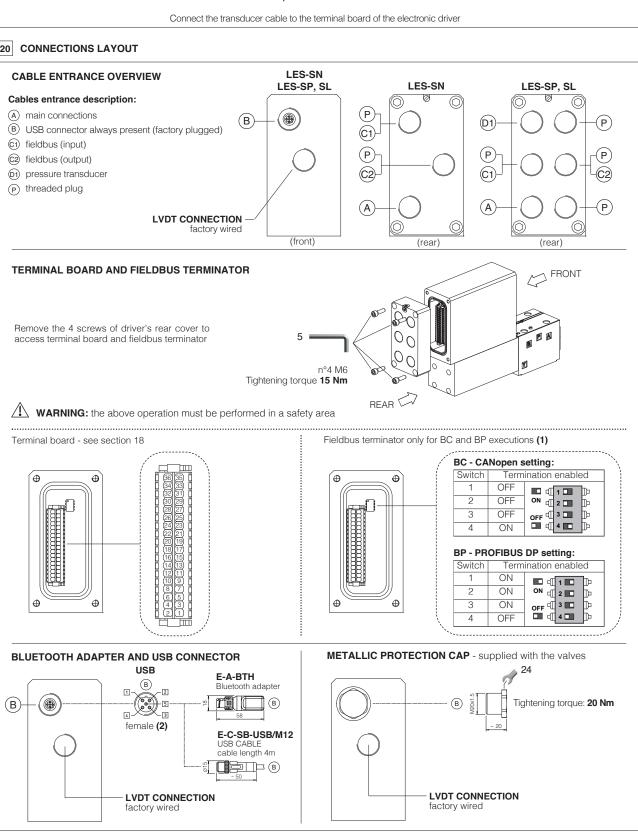
CABLE ENTRANCE	PIN	SIGNAL	TECHNICAL SPECIFICATIONS
	13	NC	do not connect
	15	TX-	Transmitter
C2	17	TX+	Transmitter
	19	RX-	Receiver
(output)	21	RX+	Receiver

# 19.6 Remote pressure transducer connector - only for SP, SL $\,$

CABLE ENTRANCES	PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES	SP, SL - Single Voltage	transducer (1) Current	SF - Double tr Voltage	ansducers (1) Current
	34	TR1	1st signal transducer ±10 Vpc / ±20 mA maximum range	Input - analog signal <b>Software selectable</b>		Connect	Connect	Connect
D1	35	AGND	Common gnd for transducer power and signals	Common gnd	Connect	/	Connect	/
	36	VF +24V	Power supply +24Vpc	Output - power supply	Connect	Connect	Connect	Connect



#### 20 CONNECTIONS LAYOUT



- (1) Drivers with BC and BP fieldbus interface are delivered by default 'Not Terminated'. All switches are set OFF
- (2) Pin layout always referred to driver's view

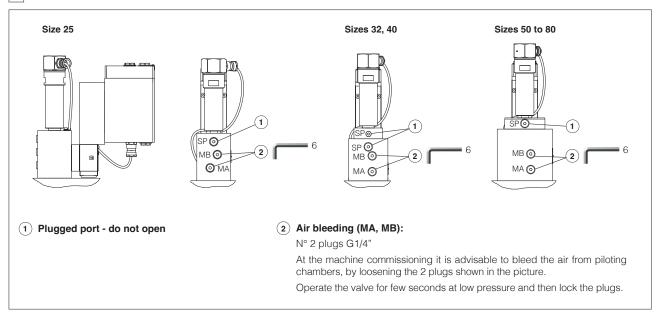
#### ${\bf 20.1~Cable~glands~and~threaded~plug~for~LES-SN}$ - see tech table ${\bf KX800}$

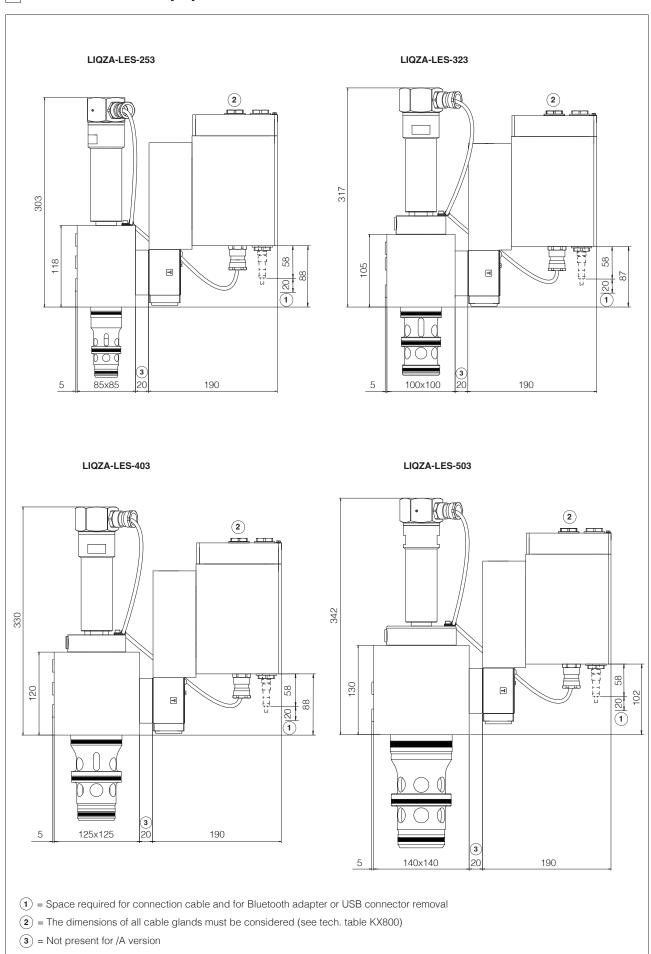
Communication	To be ordered separately				Cable entrance	Notes	
interfaces	Cable gland quantity entrance		Threaded plug quantity   entrance		overview		
NP	1	А	none	none	© © (A)	Cable entrance A is open for costumers  Cable entrance P are factory plugged	
BC, BP, EH, EW, EI, EP "via stub" connection	2	C1	1	C2		Cable entrance A, C1, C2 are open for costumers	
BC, BP, EH, EW, EI, EP "daisy chain" connection	3	C1 C2 A	none	none		Cable entrance A, C1, C2 are open for costumers	

#### 20.2 Cable glands and threaded plug for LES-SP, SL - see tech table KX800

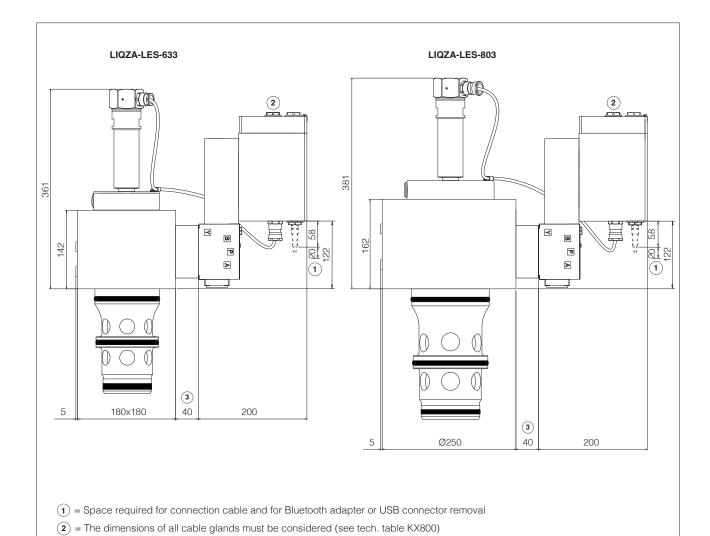
Communication	To be ordered separately			ely	Cable entrance	Notes	
interfaces	Cable gland		Threaded plug quantity entrance		overview		
NP	2	D1 A	none	none	60 P 60 P	Cable entrance A, D1 are open for costumers  Cable entrance P are factory plugged	
BC, BP, EH, EW, EI, EP "via stub" connection	3	D1 C1 A	1	C2	90 90 90 90 90 90	Cable entrance A, C1, C2, D1 are open for costumers  Cable entrance P are factory plugged	
BC, BP, EH, EW, EI, EP "daisy chain" connection	4	D1 C1 - C2 A	none	none	00 00 00 00 00 00 00 00 00 00 00 00 00	Cable entrance A, C1, C2, D1 are open for costumers  Cable entrance P are factory plugged	

# 21 AIR BLEEDING





Note: for mounting surface and cavity dimensions, see table P006



# 23 FASTENING BOLTS AND VALVE MASS

3 = Not present for /A version

Туре	Size	Fastening bolts (1) supplied with the valve	Mass [kg]
	25	4 socket head screws M12x100 class 12.9 Tightening torque = 125 Nm	15,8
	32	4 socket head screws M16x60 class 12.9 Tightening torque = 300 Nm	18,2
LIQZA	40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	23,7
LIGZA	50	4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	31,6
	63	4 socket head screws M30x120 class 12.9 Tightening torque = 2100 Nm	51,6
	80	8 socket head screws M24x80 class 12.9 Tightening torque = 1000 Nm	79,2

# 24 RELATED DOCUMENTATION

X010	Basics for electrohydraulics in hazardous environments	GX800	Ex-proof pressure transducer type E-ATRA-7
X020	Summary of Atos ex-proof components certified to ATEX, IECEx, EAC, PESO, CCC	KX800	Cable glands for ex-proof valves
FX500	Ex-proof digital proportionals with p/Q control	P006	Mounting surfaces and cavities for cartridge valves
FX900	Operating and manintenance information for ex-proof proportional valves	E-MAN	N-RA-LES TES/LES user manual
GS500	Programming tools	E-MAN	N-RA-LES-S TES/LES with p/Q control user manual
GS510	Fieldbus		