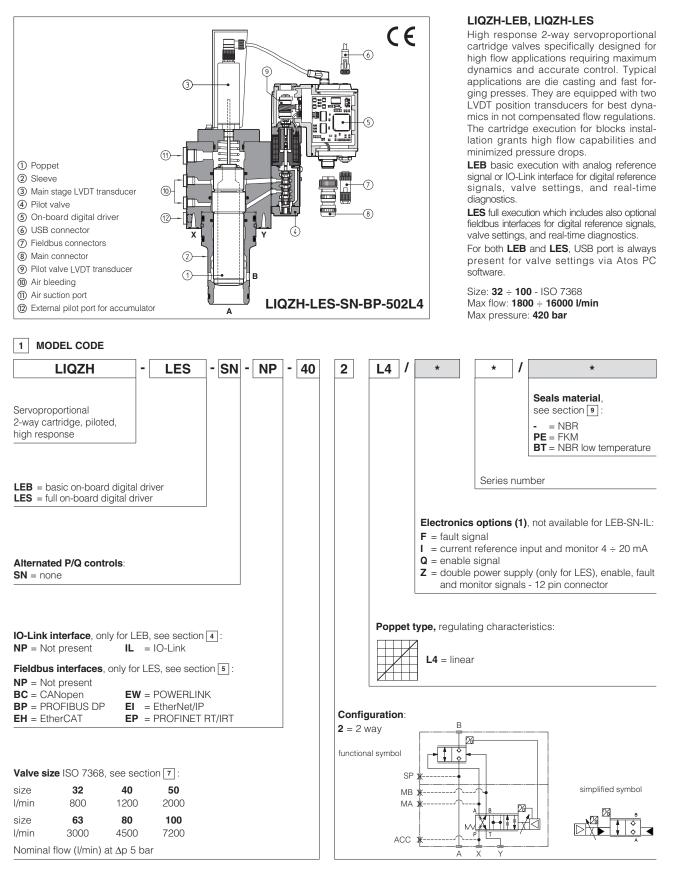
# atos 🛆

# Digital servoproportional 2-way cartridges high response

piloted, with on-board driver and two LVDT transducers



# 2 GENERAL NOTES

Atos digital proportionals valves are CE marked according to the applicable directives (e.g. Immunity and Emission EMC Directive). Installation, wirings and start-up procedures must be performed according to the general prescriptions shown in tech table **FS900** and in the user manuals included in the E-SW-\* programming software.

# 

To avoid overheating and possible damage of the electronic driver, the valves must be never energized without hydraulic supply to the pilot stage. In case of prolonged pauses of the valve operation during the machine cycle, it is always advisable to disable the driver (option /Q or /Z). A safety fuse 2,5 A installed on 24VDc power supply of each valve is always recommended, see also power supply note at sections **14**.

# 

The loss of the pilot pressure causes the undefined position of the main poppet. The sudden interruption of the power supply during the valve operation causes the immediate shut-off of the main poppet. This could cause pressure surges in the hydraulic system or high decelerations which may lead to machine damages.

## 3 VALVE SETTINGS AND PROGRAMMING TOOLS

Valve's functional parameters and configurations, can be easily set and optimized using Atos E-SW programming software connected via USB/Bluetooth to the digital driver. For fieldbus/IO-Link versions, the software permits valve's parameterization through USB/Bluetooth also if the driver is connected to the central machine unit via fieldbus/IO-Link.

 The software is available in different versions according to the driver's options (see table GS500):

 E-SW-BASIC
 support:
 NP (USB)
 IL (IO-Link)
 PS (Serial)
 IR (Infrared)

 E-SW-FIELDBUS
 support:
 BC (CANopen)
 BP (PROFIBUS DP)
 EH (EtherCAT)

 E-SW-\*/PQ
 support:
 values with SP, SF, SL alternated control (e.g. E-SW-BASIC/PQ)

WARNING: drivers USB port is not isolated! For E-C-SB-USB/M12 cable, the use of isolator adapter is highly recommended for PC protection

WARNING: see tech table GS500 for the list of countries where the Bluetooth adapter has been approved

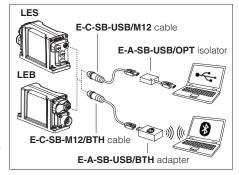
4 IO-LINK - only for LEB, see tech. table GS520

IO-Link allows low cost digital communication between the valve and machine central unit. The valve is directly connected to a port of an IO-Link master (point-to-point connection) via low-cost unshielded cables for digital reference, diagnostic and settings. The IO-Link master works as a hub exchanging this information with the machine central unit via fieldbus.

5 FIELDBUS - only for LES, see tech. table GS510

Fieldbus allows valve direct communication with machine control unit for digital reference, valve diagnostics and settings. These execution allow to operate the valves through fieldbus or analog signals available on the main connector.

#### **USB or Bluetooth connection**



# 6 GENERAL CHARACTERISTICS

Assembly position	Any position
Subplate surface finishing to ISO 4401	Acceptable roughness index: Ra ≤0,8, recommended Ra 0,4 – Flatness ratio 0,01/100
MTTFd valves according to EN ISO 13849	75 years, for further details see technical table P007
Ambient temperature range	<b>Standard</b> = $-20^{\circ}$ C $\div$ $+60^{\circ}$ C <b>/PE</b> option = $-20^{\circ}$ C $\div$ $+60^{\circ}$ C <b>/BT</b> option = $-40^{\circ}$ C $\div$ $+60^{\circ}$ C
Storage temperature range	<b>Standard</b> = $-20^{\circ}C \div +70^{\circ}C$ / <b>PE</b> option = $-20^{\circ}C \div +70^{\circ}C$ / <b>BT</b> option = $-40^{\circ}C \div +70^{\circ}C$
Surface protection	Zinc coating with black passivation, galvanic treatment (driver housing)
Corrosion resistance	Salt spray test (EN ISO 9227) > 200 h
Vibration resistance	See technical table G004
Compliance	CE according to EMC directive 2014/30/EU (Immunity: EN 61000-6-2; Emission: EN 61000-6-3) RoHS Directive 2011/65/EU as last update by 2015/863/EU REACH Regulation (EC) n°1907/2006

# 7 HYDRAULIC CHARACTERISTICS - based on mineral oil ISO VG 46 at 50 °C

Size		32	40	50	63	80	100
Max regulated flow	[l/min]						
	at $\Delta p = 5$ bar	800	1200	2000	3000	4500	7200
∆р А-В	at $\Delta p = 10$ bar	1100	1700	2800	4250	6350	10200
Max permissible flow		1800	2500	4000	6000	10000	16000
Max pressure [bar]			Ports	A, B = 420	X = 350 Y	<sup>′</sup> ≤ 10	
Nominal flow of pilot valve	at $\Delta p = 70$ bar [l/min]	20	40	40	100	100	100
Leakage of pilot valve at	P = 100 bar [l/min]	0,3	0,7	0,7	1	1	1
Piloting pressure	[bar]	min	: 40% of system	n pressure m	nax 350 recon	nmended 140 ÷	160
Piloting volume	[cm <sup>3</sup> ]	3,31	5,34	7,42	10,28	19,55	22,53
Piloting flow (1)	[l/min]	13,2	17,8	22,3	31	39	45
Response time 0 ÷ 100%	step signal (2) [ms]	15	18	20	20	30	30
Hysteresis [%	of the max regulation]			≤	0,1		
Repeatability [%	of the max regulation]			±	0,1		
Thermal drift	zero point displacement < 1% at $\Delta T = 40^{\circ}C$						

(1) With step reference input 0÷100%

(2) With pilot pressure = 140 bar, see datailed diagrams in section 10.2

# 8 ELECTRICAL CHARACTERISTICS

	1						
Power supplies	Nominal Rectified and filtere	: +24 VDC d : VRMS = 20 ÷ 32 '	VMAX (ripple max 10 °	% Vpp)			
Max power consumption	50 W	50 W					
Max. solenoid current	2,6 A	2,6 A					
Coil resistance R at 20°C	3 ÷ 3,3 Ω						
Analog input signals	Voltage: range ±10 Current: range ±20	) VDC (24 VMAX toler ) mA		bedance: $Ri > 50 k\Omega$ bedance: $Ri = 500 \Omega$			
Monitor outputs	Output range:		@ max 5 mA @ max 500 Ω load res	sistance			
Enable input	Range: 0 ÷ 5 VDC (O	FF state), 9 ÷ 24 VDC	(ON state), 5 ÷ 9 VDC	(not accepted); Input i	mpedance: Ri > 10 k $\Omega$		
Fault output	Output range: 0 ÷ 24 VDC (ON state > [power supply - 2 V]; OFF state < 1 V) @ max 50 mA; external negative voltage not allowed (e.g. due to inductive loads)				nax 50 mA;		
Alarms	Solenoid not connected/short circuit, cable break with current reference signal, over/under temperature valve spool transducer malfunctions, alarms history storage function			ver/under temperature,			
Insulation class		occurring surface ter ards ISO 13732-1 an					
Protection degree to DIN EN60529	IP66 / IP67 with mat	ing connectors					
Duty factor	Continuous rating (E	D=100%)					
Tropicalization	Tropical coating on	electronics PCB					
Additional characteristics				diagnostic (only for L inst reverse polarity of			
Communication interface	USB Atos ASCII coding	IO-Link Interface and System Specification 1.1.3	CANopen EN50325-4 + DS408	PROFIBUS DP EN50170-2/IEC61158	EtherCAT POWERLINK EtherNet/IP PROFINET IO RT/IRT IEC 61158		
Communication physical layer not insulated USB 2.0 + USB OTG		SDCI class port B	optical insulated CAN ISO11898	optical insulated RS485	Fast Ethernet, insulated 100 Base TX		
Recommended wiring cable	LiYCY shielded cab	les, see section 18					

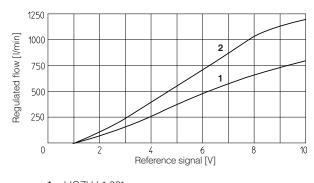
Note: a maximum time of 800 ms (depending on communication type) has to be considered between the driver energizing with the 24 V<sub>DC</sub> power supply and when the valve is ready to operate. During this time the current to the valve coils is switched to zero.

# 9 SEALS AND HYDRAULIC FLUIDS - for other fluids not included in below table, consult our technical office

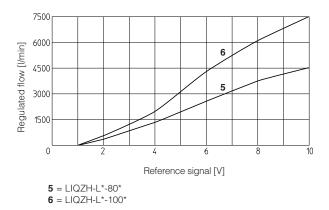
Seals, recommended fluid	temperature	NBR seals (standard) = $-20^{\circ}C \div +60^{\circ}C$ , with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$ FKM seals (/PE option) = $-20^{\circ}C \div +80^{\circ}C$ NBR low temp. seals (/BT option) = $-40^{\circ}C \div +60^{\circ}C$ , with HFC hydraulic fluids = $-20^{\circ}C \div +50^{\circ}C$				
Recommended viscosity		20÷100 mm²/s - max allowed ra	nge 15 ÷ 380 mm²/s			
Max fluid	normal operation	ISO4406 class 18/16/13 NAS1638 class 7		see also filter section at		
contamination level	longer life	ISO4406 class 16/14/11 NAS1	www.atos.com or KTF catalog			
Hydraulic fluid		Suitable seals type	Classification	Ref. Standard		
Mineral oils		NBR, FKM, NBR low temp.	HL, HLP, HLPD, HVLP, HVLPD	DIN 51524		
Flame resistant without water		FKM HFDU, HFDR		- ISO 12922		
Flame resistant with water		NBR, NBR low temp.	HFC	130 12922		

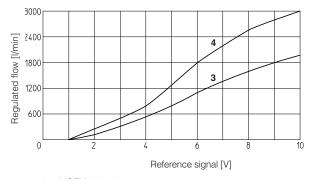
# **10 DIAGRAMS** (based on mineral oil ISO VG 46 at 50 °C)

10.1 Regulation diagrams (values measured at  $\Delta p$  5 bar)





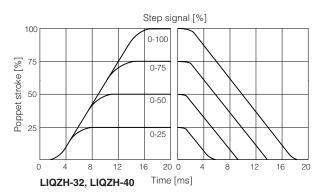


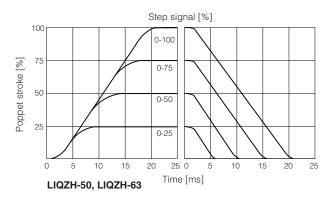


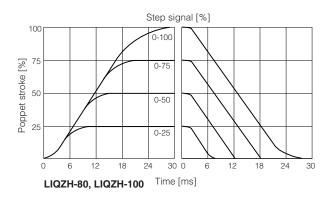


#### 10.2 Response time

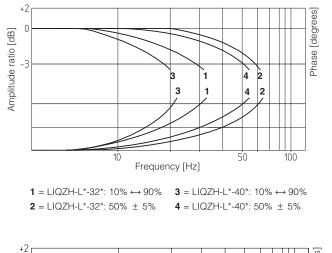
The response times in below diagrams are measured at different steps of the reference input signal. They have to be considered as average values. For the valves with digital electronics the dynamics performances can be optimized by setting the internal software parameters.

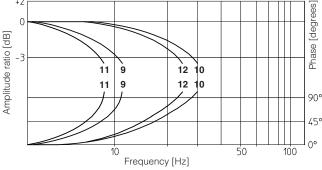




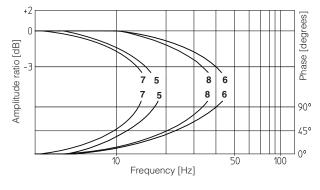


#### 10.3 Bode diagrams - stated at nominal hydraulic conditions









 $5 = LIQZH-L^*-50^*: 10\% \leftrightarrow 90\%$  $7 = LIQZH-L^*-63^*: 10\% \leftrightarrow 90\%$  $6 = LIQZH-L^*-50^*: 50\% \pm 5\%$  $8 = LIQZH-L^*-63^*: 50\% \pm 5\%$ 

#### 11 ELECTRONICS OPTIONS - not available for LEB-SN-IL

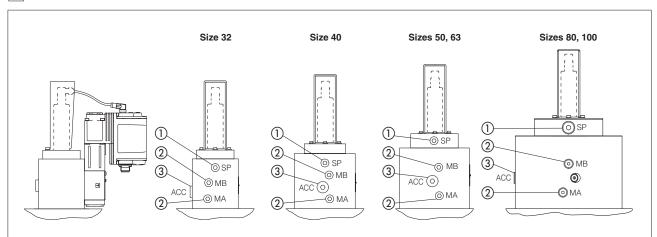
- **F** = This option permits to monitor the eventual fault condition of the driver, as for example the solenoid short circuit/not connected, reference signal cable broken for option /I, poppet position transducer broken, etc. see 14.7 for signal specifications.
- This option provides 4 ÷ 20 mA current reference and monitor signals, instead of the standard 0 ÷ 10 VDC. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of ±10 VDC or ±20 mA. It is normally used in case of long distance between the machine control unit and the valve or where the reference signal can be affected by electrical noise; the valve functioning is disabled in case of reference signal cable breakage.
- Q = This option permits to inhibit the valve function without removing the power supply to the driver. Upon disable command the current to the solenoid is zeroed and the valve's poppet moves to rest position.
   The option /Q is suggested for all cases where the valve has to be frequently inhibited during the machine cycle see 14.5 for signal specifications.

Z = This option provides, on the 12 pin main connector, the following additional features:
 Fault output signal - see above option /F
 Enable input signal - see above option /Q
 Repeat enable output signal - only for LEB-SN-NP (see 14.6)
 Power supply for driver's logics and communication - only for LES (see 14.2)

#### 12 POSSIBLE COMBINED OPTIONS

/FI, /IQ, /IZ

#### 13 AIR BLEEDING

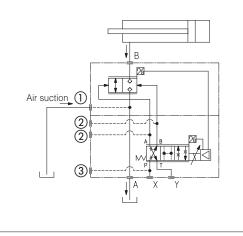


(1) To be used only in case port A is connected to tank and subjected to negative pressure, consult our technical office.

(2) At the machine commissioning it is advisable to bleed the air from piloting chambers, by loosening the 2 plugs shown in the picture. Operate the valve for few seconds at low pressure and then lock the plugs.

3 Additional external pilot port for accumulator connection.

Port	LIQZH Size						
FUIL	32	40	50	63	80	100	
(1)	G1	/4"		G1	/2"		
Air suction	C	<b>H</b> 6		CH	<b>■</b> + 10		
2			G1	/4"			
Air bleeding			C	₩ H 6			
(3)	G3/8"			G1/2"			
External pilot	CH 8			CH 10			
<u>.                                    </u>							



## 14 POWER SUPPLY AND SIGNALS SPECIFICATIONS

Generic electrical output signals of the valve (e.g. fault or monitor signals) must not be directly used to activate safety functions, like to switch-ON/OFF the machine's safety components, as prescribed by the European standards (Safety requirements of fluid technology systems and components-hydraulics, ISO 4413).

#### For **LEB-SN-IL** signals see section 16

#### 14.1 Power supply (V+ and V0)

The power supply must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers. In case of separate power supply see 14.2.

A safety fuse is required in series to each power supply: 2,5 A time lag fuse.

#### 14.2 Power supply for driver's logic and communication (VL+ and VL0) - only for /Z option

The power supply for driver's logic and communication must be appropriately stabilized or rectified and filtered: apply at least a 10000  $\mu$ F/40 V capacitance to single phase rectifiers or a 4700  $\mu$ F/40 V capacitance to three phase rectifiers.

The separate power supply for driver's logic on pin 9 and 10, allow to remove solenoid power supply from pin 1 and 2 maintaining active the diagnostics, USB and fieldbus communications.

A safety fuse is required in series to each driver's logic and communication power supply: 500 mA fast fuse.

#### 14.3 Flow reference input signal (Q\_INPUT+)

The driver controls in closed loop the valve spool position proportionally to the external reference input signal.

Reference input signal is factory preset according to selected valve code, defaults are  $\pm 10$  VDC for standard and  $4 \div 20$  mA for /l option. Input signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDC or  $\pm 20$  mA. Drivers with fieldbus interface can be software set to receive reference signal directly from the machine control unit (fieldbus reference). Analog reference input signal can be used as on-off commands with input range  $0 \div 24$ VDC.

#### 14.4 Flow monitor output signal (Q\_MONITOR) - not for /F

The driver generates an analog output signal proportional to the actual spool position of the valve; the monitor output signal can be software set to show other signals available in the driver (e.g. analog reference, fieldbus reference, pilot spool position). Monitor output signal is factory preset according to selected valve code, defaults are  $\pm 10$  VDC for standard and  $4 \div 20$  mA for /I option. Output signal can be reconfigured via software selecting between voltage and current, within a maximum range of  $\pm 10$  VDC or  $\pm 20$  mA.

#### 14.5 Enable input signal (ENABLE) - not for standard and /F

To enable the driver, supply a 24 VDC on pin 3 (pin C): Enable input signal allows to enable/disable the current supply to the solenoid, without removing the electrical power supply to the driver; it is used to active the communication and the other driver functions when the valve must be disabled for safety reasons. This condition **does not comply** with norms IEC 61508 and ISO 13849. Enable input signal can be used as generic digital input by software selection.

#### 14.6 Repeat enable output signal (R\_ENABLE) - only for LEB-SN-NP with /Z option

Repeat enable is used as output repeater signal of enable input signal (see 14.5).

#### 14.7 Fault output signal (FAULT) - not for standard and /Q

Fault output signal indicates fault conditions of the driver (solenoid short circuits/not connected, reference signal cable broken for 4 ÷ 20 mA input, spool position transducer cable broken, etc.). Fault presence corresponds to 0 VDC, normal working corresponds to 24 VDC. Fault status is not affected by the Enable input signal. Fault output signal can be used as digital output by software selection.

#### 15 IO-LINK SIGNALS SPECIFICATIONS - only for LEB-SN-IL

# 15.1 Power supply for IO-Link communication (L+ and L-)

The IO-Link master provides dedicated 24 VDc power supply for IO-Link communication. Maximum power consumption: 2 W Internal electrical isolation of power L+, L- from P24, N24

#### 15.2 Power supply for drive logic and valve regulation (P24 and N24)

The IO-Link master provides dedicated 24 Vbc power supply for valve regulation, logics and diagnostics. Maximum power consumption: 50 W Internal electrical isolation of power P24, N24 from L+, L-

#### 15.3 IO-Link data line (C/Q)

C/Q signal is used to establish communication between IO-Link master and valve.

# 16 ELECTRONIC CONNECTIONS AND LEDS

PIN	Standard	/Q	/F	TECHNICAL SPECIFICATIONS	NOTES
A	V+			Power supply 24 VDc	Input - power supply
В	V0			Power supply 0 Vbc	Gnd - power supply
С	AGND		AGND	Analog ground	Gnd - analog signal
		ENABLE		Enable (24 VDC) or disable (0 VDC) the valve, referred to V0	Input - on/off signal
D				Flow reference input signal: ±10 Vpc / ±20 mA maximum range	Input - analog signal
	Q_INPUT+			Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Software selectable
E	INPUT-			Negative reference input signal for Q_INPUT+	Input - analog signal
	Q_MONITOF	referred to:		Flow monitor output signal: ±10 Vpc / ±20 mA maximum range	Output - analog signal
F	AGND	VO		Defaults are 0 ÷ 10 Vpc for standard and 4 ÷ 20 mA for /I option	Software selectable
			FAULT	Fault (0 Vbc) or normal working (24 Vbc)	Output - on/off signal
G	EARTH			Internally connected to the driver housing	

# 16.1 Main connector signals - 7 pin - standard, /F and /Q options $\widehat{\mbox{A1}}$

#### 16.2 Main connector signal - 12 pin - /Z option (A2)

PIN	LEB /Z	LES /Z	TECHNICAL SPECIFICATIONS	NOTES
	V+		Power supply 24 Vbc	Input - power supply
1	V0		Power supply 0 VDc	Gnd - power supply
2 3	ENABLE rei	erred to:	Enable (24 Vbc) or disable (0 Vbc) the valve	Input - on/off signal
4	Q_INPUT+	1	Flow reference input signal: ±10 Vbc / ±20 mA maximum range Defaults are 0 ÷ 10 Vbc for standard and 4 ÷ 20 mA for /l option	Input - analog signal Software selectable
5	INPUT-		Negative reference input signal for Q_INPUT+	Input - analog signal
6	Q_MONITOF AGND	referred to: VL0	Flow monitor output signal: ±10 Vbc / ±20 mA maximum range Defaults are 0 ÷ 10 Vbc for standard and 4 ÷ 20 mA for /l option	Input - analog signal Software selectable
7	AGND		Analog ground	Output - analog signal
1		NC	Do not connect	Gnd - analog signal
8	R_ENABLE		Repeat enable, output repeater signal of enable input, referred to V0	Output - on/off signal
0		NC	Do not connect	
9	NC		Do not connect	
9		VL+	Power supply 24 Vbc for driver's logic and communication	Input - power supply
10	NC		Do not connect	
10		VL0	Power supply 0 Vbc for driver's logic and communication	Gnd - power supply
11 PE	FAULT refer	rred to: VL0	Fault (0 Vbc) or normal working (24 Vbc)	Output - on/off signal
	EARTH		Internally connected to the driver housing	

Note: do not disconnect VL0 before VL+ when the driver is connected to PC USB port

# 16.3 IO-Link connector signals - M12 - 5 pin - Coding A, port class B A only for LEB-SN-IL

PIN	SIGNAL	TECHNICAL SPECIFICATIONS	NOTES
1	L+	Power supply 24 Vbc for IO-Link communication	Input - power supply
2	P24	Power supply 24 Vbc for valve regulation, logics and diagnostics	Input - power supply
3	L-	Power supply 0 Vpc for IO-Link communication	Gnd - power supply
4	C/Q	IO-Link data line	Input / Output - signal
5	N24	Power supply 0 Vbc for valve regulation, logics and diagnostics	Gnd - power supply

Note: L+, L- and P24, N24 are electrically isolated

# 16.4 Communications connectors B - C

	B USB connector - M12 - 5 pin always present				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	+5V_USB	Power supply			
2	ID	Identification			
3	GND_USB	Signal zero data line			
4	D-	Data line -			
5	D+	Data line +			

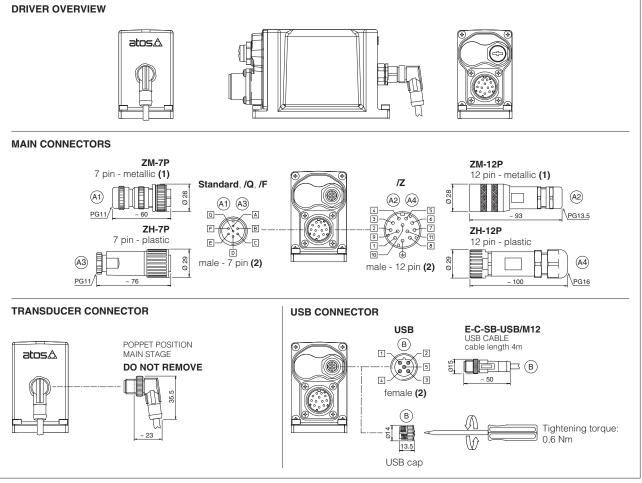
C1 (	C1 $C2$ BP fieldbus execution, connector - M12 - 5 pin			
PIN	SIGNAL	<b>TECHNICAL SPECIFICATION</b> (1)		
1	+5V	Termination supply signal		
2	LINE-A	Bus line (high)		
3	DGND	Data line and termination signal zero		
4	LINE-B	Bus line (low)		
5	SHIELD			

©1 (	C1 $C2$ BC fieldbus execution, connector - M12 - 5 pin				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	CAN_SHLD	Shield			
2	not used	(c) - (c) pass-through connection (2)			
3	CAN_GND	Signal zero data line			
4	CAN_H	Bus line (high)			
5	CAN_L	Bus line (low)			

©1 (	©1 ©2 EH, EW, EI, EP fieldbus execution, connector - M12 - 4 pin				
PIN	SIGNAL	TECHNICAL SPECIFICATION (1)			
1	TX+	Transmitter			
2	RX+	Receiver			
3	TX-	Transmitter			
4	RX-	Receiver			
	SHIELD				

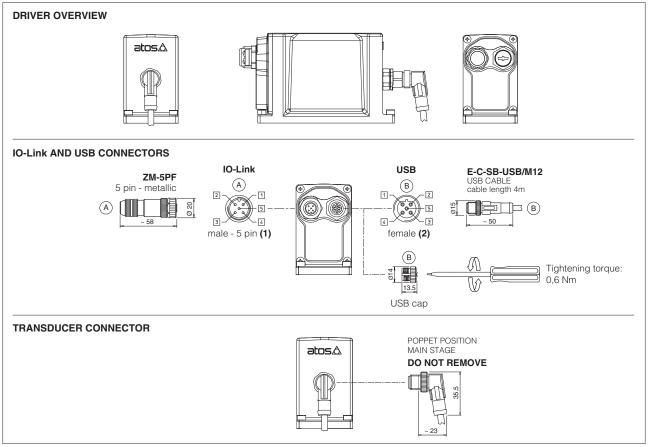
(1) shield connection on connector's housing is recommended

(2) Pin 2 can be fed with external +5V supply of CAN interface

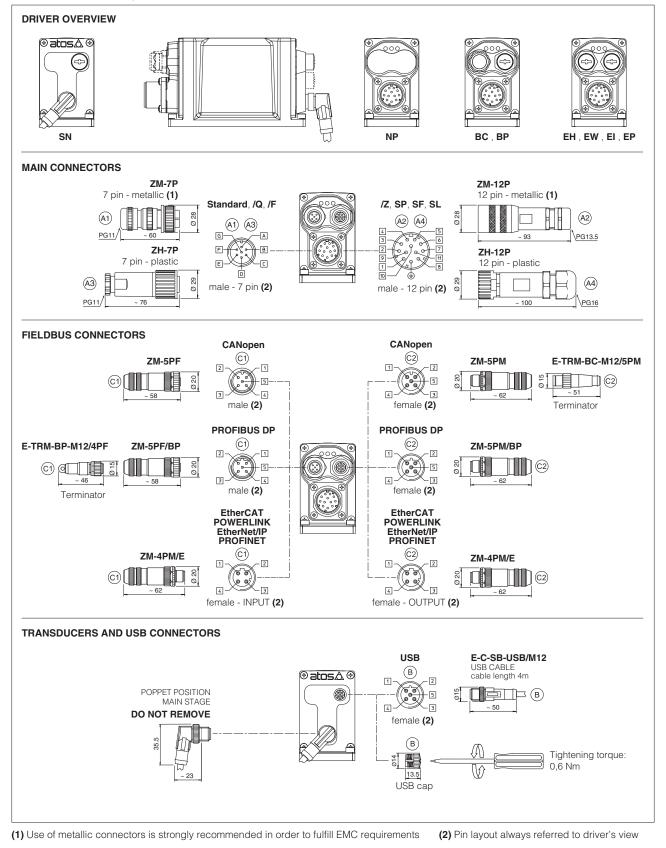


(1) Use of metallic connectors is strongly recommended in order to fulfill EMC requirements (2) Pin layout always referred to driver's view

#### 16.6 LEB-SN-IL connections layout



(1) Pin layout always referred to driver's view



#### 16.8 Diagnostic LEDs - only for LES

Three leds show driver operative conditions for immediate basic diagnostics. Please refer to the driver user manual for detailed information.

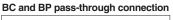
FIELDBUS	NP Not Present	BC CANopen	BP PROFIBUS DP	EH EtherCAT	EW POWERLINK	EI EtherNet/IP	EP PROFINET	L1 L2 L3
L1	VALVE STATUS			LINK/ACT				
L2	NETWORK STATUS		NETWORK STATUS					
L3	SOLENOID STATUS			LINK/ACT				

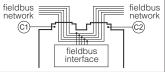
# 17 IN / OUT FIELDBUS COMMUNICATION CONNECTORS

Two fieldbus communication connectors are always available for digital drivers executions BC, BP, EH, EW, EI, EP. This features allows considerable technical advantages in terms of installation simplicity, wirings reduction and also avoid the usage expensive T-connectors.

For BC and BP executions the fieldbus connectors have an internal pass-through connection and can be used like end point of the fieldbus network, using an external terminator (see tech table **GS500**).

For EH, EW, EI and EP executions the external terminators are not required: each connector is internally terminated.





## **18 CONNECTORS CHARACTERISTICS** - to be ordered separately

#### 18.1 Main connectors - 7 pin

CONNECTOR TYPE	POWER SUPPLY AND SIGNALS	POWER SUPPLY AND SIGNALS		
CODE (A1) ZM-7P		A3 ZH-7P		
Туре	7pin female straight circular	7pin female straight circular		
Standard According to MIL-C-5015		According to MIL-C-5015		
Material Metallic		Plastic reinforced with fiber glass		
Cable gland	PG11	PG11		
Recommended cable	LiYCY 7 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply) or LiYCY 7 x 1 mm <sup>2</sup> max 40 m (logic and power supply)	LiYCY 7 x 0,75 mm <sup>2</sup> max 20 m (logic and power supply) or LiYCY 7 x 1 mm <sup>2</sup> max 40 m (logic and power supply)		
Conductor size up to 1 mm <sup>2</sup> - available for 7 wires		up to 1 mm <sup>2</sup> - available for 7 wires		
Connection type to solder		to solder		
Protection (EN 60529)	IP 67	IP 67		

#### 18.2 Main connectors - 12 pin

CONNECTOR TYPE	POWER SUPPLY AND SIGNALS	POWER SUPPLY AND SIGNALS		
CODE	(A2) ZM-12P			
Туре	12pin female straight circular	12pin female straight circular		
Standard	DIN 43651	DIN 43651		
Material Metallic		Plastic reinforced with fiber glass		
Cable gland PG13,5		PG16		
Recommended cable         LiYCY 12 x 0,75 mm² max 20 m (logic and power supply)		LiYCY 10 x 0,14mm² max 40 m (logic) LiYY 3 x 1mm² max 40 m (power supply)		
Conductor size 0,5 mm <sup>2</sup> to 1,5 mm <sup>2</sup> - available for 12 wires		0,14 mm <sup>2</sup> to 0,5 mm <sup>2</sup> - available for 9 wires 0,5 mm <sup>2</sup> to 1,5 mm <sup>2</sup> - available for 3 wires		
Connection type	to crimp	to crimp		
Protection (EN 60529) IP 67		IP 67		

#### 18.3 IO-Link connector - only for LEB-SN-IL

CONNECTOR TYPE	IL IO-Link				
CONNECTOR TIPE					
CODE	A ZM-5PF				
Туре	5pin female straight circular				
Standard	M12 coding A – IEC 61076-2-101				
Material	Metallic				
Cable gland	Pressure nut - cable diameter 6÷8 mm				
Recommended cable	5 x 0,75 mm² max 20 m				
Connection type	screw terminal				
Protection (EN 60529)	IP 67				

#### 18.4 Fieldbus communication connectors

CONNECTOR TYPE	BC CANopen (1)		BP PROFI	<b>BUS DP</b> (1)	EH EtherCAT, EW POWERLINK, EI EtherNet/IP, EP PROFINET (2)	
CODE	C1 ZM-5PF	©2) ZM-5PM	C1 ZM-5PF/BP	C2 ZM-5PM/BP	C1 C2	ZM-4PM/E
Туре	5 pin female straight circular	5 pin male straight circular	5 pin female straight circular	5 pin male straight circular		4 pin male straight circular
Standard	M12 coding A – IEC 61076-2-101		M12 coding B – IEC 61076-2-101		M12 coding D – IEC 61076-2-101	
Material	Metallic		Metallic			Metallic
Cable gland	Pressure nut - cable diameter 6÷8 mm		Pressure nut - cable diameter 6÷8 mm		Pressure n	ut - cable diameter 4÷8 mm
Cable	CANbus Standard (DR 303-1)		PROFIBUS DP Standard		Ethe	rnet standard CAT-5
Connection type	screw terminal		screw terminal		terminal block	
Protection (EN 60529)	IP67		IP 67		IP 67	

(1) E-TRM-\*\* terminators can be ordered separately - see tech table GS500

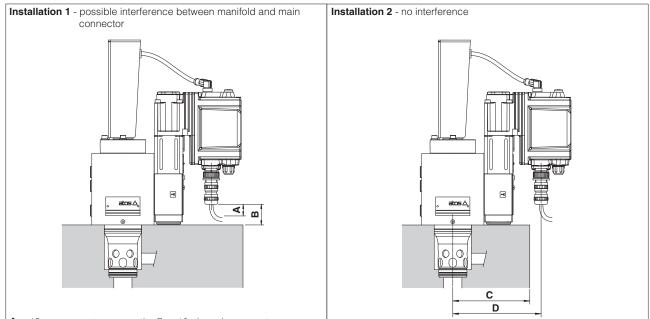
(2) Internally terminated

# 19 FASTENING BOLTS AND VALVE MASS

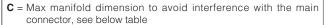
Туре	Size	Fastening bolts (1)	Mass [kg]		
	32	4 socket head screws M16x60 class 12.9 Tightening torque = 300 Nm	12,4		
	40	4 socket head screws M20x70 class 12.9 Tightening torque = 600 Nm	18,0		
LIQZH	50	4 socket head screws M20x80 class 12.9 Tightening torque = 600 Nm	26,0		
	63	4 socket head screws M30x120 class 12.9 Tightening torque = 2100 Nm	46,9		
	80	8 socket head screws M24x80 class 12.9 Tightening torque = 1000 Nm	75,0		
	100	8 socket head screws M30x120 class 12.9 Tightening torque = 2100 Nm	128,4		

(1) Fastening bolts supplied with the valve

#### 20 MAIN CONNECTORS INSTALLATION DIMENSIONS



- $\mathbf{A}$  = 15 mm space to remove the 7 or 12 pin main connectors
- B = Clearance between main connector to valve's mounting surface.
   See the below table to verify eventual interferences, depending to the valve size and connector type

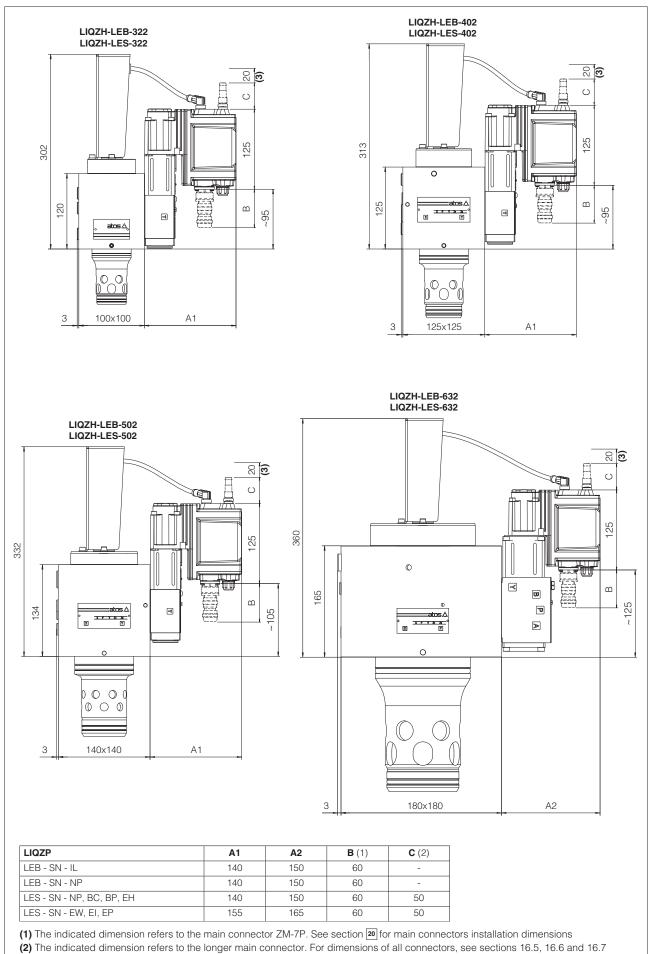


Reference dimension	Main connector code	Valve size						
		32	40	50	63	80	100	
В	ZM-7P	35	35	45	65	65	80	
	ZH-7P	(1)	(1)	29	52	52	67	
	ZM-12P	(1)	(1)	(1)	32	32	47	
	ZH-12P	(1)	(1)	(1)	(1)	(2)	40	
<b>C</b> (max)	-	121	134	141	172	202	229	
D	-	141	154	161	192	222	249	

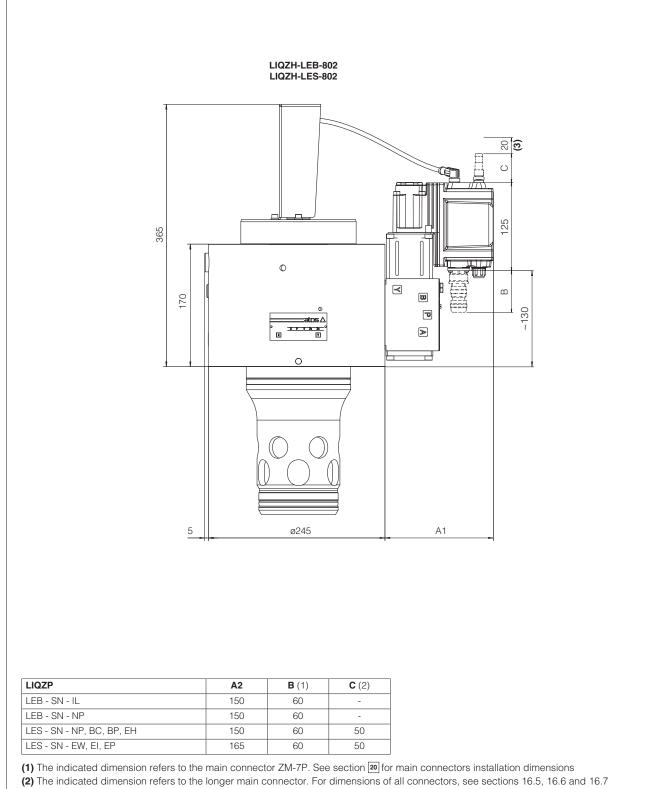
Above dimenions refer to the main connector fully screwed to driver's connector. The space **A** = 15 mm to remove the connector must be considered (1) The connector installation can be performed only if the valve's driver protrudes from the edge of the relevant mounting manifold as rapresented in above "Installation 2"

(2) The connector installation may be critic, depending to the cable size and bending radius

# 21 INSTALLATION DIMENSIONS [mm]

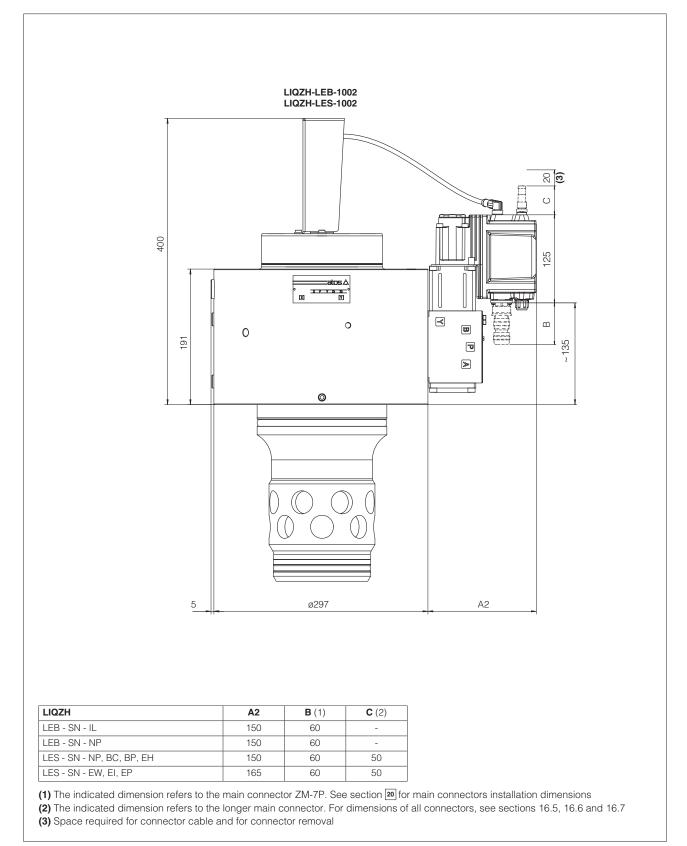


(3) Space required for connector cable and for connector removal



(3) Space required for connector cable and for connector removal

Note: for mounting surface and cavity dimensions, see table P006



Note: for mounting surface and cavity dimensions, see table P006

# 22 RELATED DOCUMENTATION

FS001	Basics for digital electrohydraulics	K800	Electric and electronic connectors
FS900	Operating and maintenance information for proportional valves	P006	Mounting surfaces and cavities for cartridge valves
GS500 GS510 GS520	Programming tools Fieldbus IO-Link interface		-RI-LEB TEB/LEB user manual -RI-LES TES/LES user manual